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1 Introduction

1.1 About this Manual

This manual provides to you descriptions about the netSCOPE instrument driver in LabVIEW.

For the netSCOPE data processing in LabVIEW you only need to perform a view programming steps.

1.1.1 Online Help

The netSCOPE VIs in LabVIEW contains an integrated online help facility.

➢ To open the online help, click on Help or press F1.

1.1.2 List of Revisions

<table>
<thead>
<tr>
<th>Index</th>
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<th>Version</th>
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<td>01</td>
<td>13-11-12</td>
<td>netSCOPE for LabVIEW Instrument Driver</td>
<td>1.0.x.x</td>
<td>All</td>
<td>Created</td>
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</tbody>
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Table 1: List of Revisions
1.1.3 Conventions in this Manual

Notes, operation instructions and results of operation steps are marked as follows:

Notes

![Important: <important note>]

![Note: <note>]

![<note, where to find further information>]

Operation Instructions

1. <instruction>
2. <instruction>

or

➢ <instruction>

Results

➢ <result>
1.2 Legal Notes

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2 Overview

2.1 About netSCOPE for LabVIEW

netSCOPE uses LabVIEW as software frontend. The netSCOPE device is delivered with the LabVIEW instrument driver interface.

The netSCOPE device gets process data from the automation network and provides the process data to LabVIEW. Users can program their application in LabVIEW. In LabVIEW

1. first, the netSCOPE data recording card is initialized,
2. then the signals to be detected are parameterized,
3. then, the process values can be recorded and processed in LabVIEW.
4. After the measurement is complete, the netSCOPE data recording card is closed.

Use Cases

- Machine condition monitoring / visualization
  The netSCOPE device acquires process data
  The user implements condition monitoring tasks and visualization in LabVIEW.
- Process documentation
  netSCOPE device acquires process data
  User implements documentation tasks and database connection in LabVIEW.

Generic Variable Definition

Note: If possible avoid to use specific variable definitions. Instead use generic variable definitions. This allows you to reuse the variable definitions for other systems.
2.2 netSCOPE System Data Flow

The netSCOPE for LabVIEW instrument driver supports process data recording with multiple netSCOPE data acquisition cards at the same time. The process data captured from the network is stored in an individual ring buffer of the PC. Depending on the user configuration, the ring buffer is being created either in the main memory (RAM) or on the hard drive (HDD). The ring buffer data is then being converted to be displayed in LabVIEW using the "Get Data.vi" function. In LabVIEW the acquisition data can be shown in a diagram or histogram, for example.

![Diagram of netSCOPE System Data Flow](image)

*Figure 1: netSCOPE System Data Flow*
3 Instrument Driver for LabVIEW

3.1 Opening LabVIEW, netSCOPE.lvlib and VI

- Open LabVIEW.

- Select netSCOPE.lvlib.

- The netSCOPE.lvlib on Main Application Instance / Items window is displayed.

- Select the Items tab.

- Select netSCOPE.lvlib.
Double click to the VI you need (e.g. Interactive Example.vi).

You can use

- the netSCOPE VIs in the folder Examples to understand how to create the netSCOPE programming in LabVIEW.
- The VIs in the folder Public to create your netSCOPE programming.

The Front Panel view of the corresponding VI is opened (e.g. Interactive Example.vi, see section netSCOPE.lvlib:Interactive Example.vi on page 13).
3.2 Examples

3.2.1 netSCOPE.lvlib:Interactive Example.vi

The netSCOPE.lvlib:Interactive Example.vi example shows how to import variables from ENI file and how to add a variable manually or to edit a value and respectively how to visualize the resulting data.

![Figure 4: netSCOPE.lvlib:Interactive Example.vi](image)

3.2.1.1 Open Front Panel, Select Interface, Select Device Frontpanel

In the LabVIEW netSCOPE.lvlib on Main Application Instance / Items pane:

- Select the Items tab > netSCOPE.lvlib > Examples.
- Double click to Interactive Example.vi.

The Front Panel view of the netSCOPE.lvlib:Interactive Example.vi is opened.

![Figure 5: netSCOPE.lvlib:Interactive Example.vi - Front Panel](image)

- Click Run.
Select Interface is enabled.

Click on Select Interface.

The Select Device Frontpanel pane is opened:
In the Select Device Frontpanel pane:

- Select the Target System: “EtherCAT”.
- Click Identify device, to identify your device (optionally).
- The STA0 and the STA1 LED at the netSCOPE data acquisition card blink green for approx 10 sec.
- Click Select device and select your device.
- The Select Device Frontpanel pane is closed.

3.2.1.2 Configure Variables

- Configure Variables and Set Bus Active are enabled.

![Figure 8: netSCOPE.lvlib:Interactive Example.vi - Front Panel](image)

- Click on Configure Variables.
- The netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi pane is opened.
Select the required ENI file (*.xml).
Select **Import variables from ENI**.
The imported variables are listed in the **Available Variables** table.
Under **Available Variables** you can remove a variable, clear all variables, add a variable manually or edit a variable.

**Remove selected:**
To remove a variable from the **Available Variables** list:
- Select the variable to be removed.
- Click on **Remove selected**.

**Clear list:**
To clear the total **Available Variables** list:
- Click on **Clear list**.

**Manually add variable:**
To add a variable manually to the **Available Variables** list:
- Click on **Manually add variable**.
- The **netSCOPE.lvlib: Add or Modify Variable Dialog.vi** pane is displayed.

![Figure 11: netSCOPE.lvlib: Add or Modify Variable Dialog.vi](image)

- Enter the single variable definition values as described in the table **Supported Data Types in EtherCAT** on page 75.
- Click on **Add Variable** (below the entry fields).
- The variable definition values for the new variable are stored and the `netSCOPE.lvlib: Add or Modify Variable Dialog.vi` pane is closed.

**Edit variable:**
To edit a variable given in the **Available Variables** list:
- Click on **Edit variable**.
- The `netSCOPE.lvlib: Add or Modify Variable Dialog.vi` pane is displayed showing the variable definition values of the selected variable.

![Figure 12: netSCOPE.lvlib: Add or Modify Variable Dialog.vi](image)

The single variable definition values as described in the table **Supported Data Types in EtherCAT** on page 75.
- Edit or change the values.
- Click on **Modify Variable** (below the entry fields).
- The variable definition values are changes and the `netSCOPE.lvlib: Add or Modify Variable Dialog.vi` pane is closed.
3.2.1.3 Show in waveform

- In the netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi pane put a variable from the Available Variable list by drag & drop to the Show in waveform1 list.

![Figure 13: netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi](image)

Under Show in waveform1 you can remove a variable and clear all variables.

### Remove selected:
To remove a variable from the Show in waveform1 list:
- Select the variable to be removed.
- Click on Remove selected.

### Clear list:
To clear the total Show in waveform1 list:
- Click on Clear list.
Done

- Click on **Done**.
- The `netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi` pane is closed.
- The newly defined variables are saved.

### 3.2.1.4 Set Bus Active / Set Bus Inactive

- Select **Set Bus Active**.

**Figure 14: netSCOPE.lvlib:Interactive Example.vi - Front Panel**

- Via **Set Bus Active** the netSCOPE data acquisition card is started
- **Set Bus Active** changes to **Set Bus Inactive**.
- The netSCOPE data acquisition card is activated on the bus and ready for data capturing. The measurement and data capturing are not yet started.
3.2.1.5 Start Capture

- Select **Start Capture**.

Figure 15: netSCOPE.lvlib:Interactive Example.vi - Front Panel

- Via **Start Capture** the measurement and data capturing are started.
- **Start Capture** changes to **Stop Capture**.
- In the **Event List** (below) any possible notification events (states or error states) are listed. See section *Notification Events* on page 56.
The display shows the measured and captured data, which are transferred from the Slave to the Master. The history of the variable gets visible. Any values transferred at the bus get visible (inputs, outputs, default values, counter, sinus signals etc.).

![Figure 16: netSCOPE.lvlib:Interactive Example.vi - Front Panel (Example: 4 Bytes in cyclic)](image)

### 3.2.1.6 Stop Capture, Set Bus inactive, STOP

- To stop the capturing process click on **Stop Capture**.
- To set the Bus inactive, click on **Set Bus Inactive**.
- To stop the netSCOPE.lvlib:Interactive Example.vi click on **STOP**.

**Note:** When STOP has been selected, for another measuring and capturing cycle the ENI file must be loaded newly.

**Important:** Do not use the LabVIEW’s **Abort Execution** to stop the capturing and measuring process. Instead of this, use **Stop Capture, Set Bus inactive** and **STOP**.
3.2.2 netSCOPE.lvlib:Simple Example.vi

The netSCOPE.lvlib:Simple Example.vi shows the minimal programming effort which is needed to acquire a single process data signal from a netSCOPE device.

Figure 17: netSCOPE.lvlib:Simple Example.vi

3.2.2.1 Open Front Panel

In the LabVIEW netSCOPE.lvlib on Main Application Instance / Items pane:

1. Open Frontpanel
   - Select the Items tab > netSCOPE.lvlib > Examples.
   - Double click to Simple Example.vi.
   - The Front Panel view of the netSCOPE.lvlib:Simple Example.vi is opened.

   Figure 18: netSCOPE.lvlib:Simple Example.vi - Front Panel

2. Open Block Diagram.
   - Double click to the netSCOPE.lvlib:Simple Example.vi Front Panel.
   - The netSCOPE.lvlib:Simple Example.vi Block Diagram is opened (see figure netSCOPE.lvlib:Simple Example.vi on page 23).

3. Enter or change data manually.
   - Under My variable name: Enter the name of the variable to display (regexp).
Under **Change to path for ENI file**: Select the path to the ENI file to be loaded.

Under **Change to data type the variable has**: Manually select the data type of the variable which shall be displayed.

Under **Number of values to display**: Enter or change the number of samples which can be viewed in the graph at the same time.

**Figure 19: netSCOPE.lvlib:Simple Example.vi Block Diagram - Slope for Manual Data Input**

4. Start Visualization
   - Change to the **netSCOPE.lvlib:Simple Example.vi Front Panel**.
   - Click to Run.
   - The values of the variable are displayed in the XY graph over Time diagram.

5. Stop Visualization
   - To stop the visualization click on **STOP**.
3.2.2.2 netSCOPE.lvlib:Simple Example.vi Block Diagram

Figure 20: netSCOPE.lvlib:Simple Example.vi Block Diagram
The netSCOPE.lvlib:Simple Example.vi Block Diagram (see figure netSCOPE.lvlib:Simple Example.vi Block Diagram on page 25) shows the VIs required to visualize the values of a certain variable and how they are connected to each other in the block diagram from the left side to the right side:

- **Initialize System.vi:**
  ![Initialize System.vi](image)
  This driver VI initializes the netSCOPE system. This is the first VI to be called before any other netSCOPE VI is useable. For details see section netSCOPE.lvlib:Initialize System.vi on page 86.

- **Get Instrument List.vi:**
  ![Get Instrument List.vi](image)
  This driver VI returns a list of all instruments of the system. For details see section netSCOPE.lvlib:Get Instrument List.vi on page 77.

- **Connection to the device:**
  ![Connection to the device](image)
  The first netSCOPE device is selected.

- **Initialize Instrument.vi:**
  ![Initialize Instrument.vi](image)
  This VI initializes one instrument specified by its name. This VI must be called once before using any instrument specific VIs. For details see section netSCOPE.lvlib:Initialize Instrument.vi on page 85.

- **Ringbuffer Configuration.vi**
  ![Ringbuffer Configuration.vi](image)
  Configures the ringbuffer storage size in Megabytes and location.
  - RAM storage location does not need a save path.
  - HDD storage location needs a save path to be specified.
  Note, that HDD storage is most likely less performant than RAM storage. For details see section netSCOPE.lvlib:Ringbuffer Configuration.vi on page 57.
- Manual Data Input:
  
  **My variable name:** To enter the name of variable to be displayed (regexp)

  **Change to path for ENI file:** The path to the ENI file to be loaded must be selected. The ENI file contains all variables and its values.

  **Change to data type the variable has:** To manually select the data type of the variable which shall be displayed.

  **Number of values to display:** Allows to enter or change the number of samples which can be viewed in the graph at the same time.

- **EtherCAT Load ENI File.vi:**

  This EtherCAT specific VI loads all variables from the given ENI file. For details see section `netSCOPE.lvlib:EtherCAT Load ENI File.vi` on page 72.

- **Set Bus Active.vi:**

  Activates the physical connection to the communication bus or network. This is a prerequisite before calling the Start Capture VI. For details see section `netSCOPE.lvlib:Set Bus Active.vi` on page 49.

- **Start Capture.vi:**

  Starts the capture task for process data values. This requires the bus to be activated via the Set Bus Active VI. For details see section `Start Capture` on page 21.

- **Get Variable IDs by Name.vi:**

  Returns a list of variables IDs for all variables which's name matches the given regular expression. For details see section `netSCOPE.lvlib:Get Variable IDs by Name.vi` on page 79.
- **Data Visualization:**
  The variable is visualized.

![Figure 21: netSCOPE.lvlib:Simple Example.vi Block Diagram - Loop for Data Visualization](image)

- **netSCOPE.lvlib:Get Capture Buffer State.vi:**
  
  ```vii
  instrument handle in
  error in (no error)
  buffer fill level %
  current write position %
  oldest stored time
  newest stored time
  error out
  ```
  
  Gets the current state of the capture ring buffer. For details see section **netSCOPE.lvlib:Get Capture Buffer State.vi** on page 44.

- **Read Data.vi:**
  
  ```vii
  instrument handle in
  read to timestamp
  read from timestamp
  variable ID
  timestamp list in
  value list in
  status list in
  error in (no error)
  count of read values
  timestamp list out
  value list out
  status list out
  error out
  ```
  
  Reads a variables value from the capture data ring buffer. Reading is limited to the time span given, from time must always be specified.
  
  The maximum amount of data that is read out is implicitly specified by the input array size. All input arrays (timestamp list, value list, status list) must have the same size. The value list contains elements which must be preinitialized with the LabVIEW data type and its expected size. The amount of actually read values is returned by "count of read values" if this value is smaller than the array size, the rest of the arrays elements do not contain correct data and must be ignored. The VI does not resize the arrays automatically. For details see section **netSCOPE.lvlib:Read Data.vi** on page 60.
- **Stop Capture.vi:**

  ```plaintext
  instrument handle in           instrument handle out
  error in (no error)           error out
  ```

  Stops the capture task for process data values. After stopping no new data will be stored in the capture ring buffer, but yet captured data is still available. For details see section `netSCOPE.lvlib:Stop Capture.vi` on page 52.

  - **Set Bus Inactive.vi:**

    ```plaintext
    instrument handle in           instrument handle out
    error in (no error)           error out
    ```

    Deactivates the physical connection to the communication bus or network.

    If a capture is running is must be stopped via the Stop Capture VI first.

    For details see section `netSCOPE.lvlib:Set Bus Inactive.vi` on page 50.

  - **Close Instrument.vi:**

    ```plaintext
    instrument handle       system handle
    error in (no error)     error out
    ```

    Closes an instrument and returns the system handle the instrument belongs to. This will discard all configurations and captured ring buffer data for this instrument. The Instrument will not be accessible anymore unless it is reopened via the Initialize Instrument VI. For details see section `netSCOPE.lvlib:Close Instrument.vi` on page 83.

  - **Close System.vi:**

    ```plaintext
    system handle
    error in (no error)     error out
    ```

    Closes a system. All instruments belonging to this system will be closed automatically, all captured ringbuffer data in this system will be discarded. For details see section `netSCOPE.lvlib:Close System.vi` on page 84.

  - **Error Description.vi:**

    ```plaintext
    error descriptions out
    error codes out
    ```

    This VI returns all netSCOPE specific error codes and descriptions. Useful to be connected to the General Error Handler VIs [user-defined codes] and [user-defined descriptions] inputs. For details see section `netSCOPE.lvlib:Close System.vi` on page 84.
3.3 Examples - Helpers

3.3.1 netSCOPE.lvlib:Select Device Frontpanel.vi

The netSCOPE.lvlib:Select Device Frontpanel.vi example represents a subfunction of the netSCOPE.lvlib:Interactive Example.vi (see section Open Front Panel, Select Interface, Select Device Frontpanel on page 13) and includes the subfunctions Select the Target System, Identify device and Select device.

![Diagram of netSCOPE.lvlib:Select Device Frontpanel.vi]

**system handle in** Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).

**instrument list** A list of available instruments found on the system. The instrument list is created by “Get Instrument List.vi” (see section netSCOPE.lvlib:Get Instrument List.vi page 77).

**error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

**system handle out** Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).

**system ID** Selected target system identifier.

**instrument name** Name of the selected instrument (for example “netSCOPE”).

**error out** contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.

**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

3.3.1.1 Select Device Frontpanel

In the LabVIEW netSCOPE.lvlib on Main Application Instance / Items pane:

- Select the Items tab > netSCOPE.lvlib > Examples > Helpers.
- Double click to netSCOPE.lvlib:Select Device Frontpanel.vi.
- The Front Panel view of the netSCOPE.lvlib:Select Device Frontpanel.vi is opened.

![Image of Select Device Frontpanel.vi]

Figure 23: netSCOPE.lvlib: Select Device Frontpanel.vi - Front Panel

- Click Run.
- The netSCOPE.lvlib:Select Device Frontpanel.vi is in Run mode:
In the **netSCOPE.lvlib:Select Device Frontpanel.vi** pane:

- Select the **Target System**: “EtherCAT”.
- Click **Identify device**, to identify your device (optionally).
- The STA0 and the STA1 LED at the netSCOPE data acquisition card blink green for approx 10 sec.
- Click **Select device** and select your device.
- The **netSCOPE.lvlib:Select Device Frontpanel.vi** is in **Stop** mode:
3.4 Examples - Helpers - EtherCAT

3.4.1 netSCOPE.lvlib:EtherCAT Add or Modify Variable Dialog.vi

- Adds or modifies the EtherCAT-specific definition of the given variable.
- EtherCAT-specific VI.

![Figure 25: netSCOPE.lvlib:EtherCAT Add or Modify Variable Dialog.vi](image)

- **instrument handle in** identifies a particular instrument session.
- **variable ID** Identifier of the existing variable that should be modified.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the **instrument handle**.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.4.1.1 Open Front Panel, configure Variable

In the LabVIEW netSCOPE.lvlib on Main Application Instance / Items pane:

- Select the Items tab > netSCOPE.lvlib > Examples > Helpers > EtherCAT.
- Double click to netSCOPE.lvlib:EtherCAT Add or Modify Variable Dialog.vi.
- The Front Panel view of the netSCOPE.lvlib: Add or Modify Variable Dialog.vi is displayed.
- Click Run.
- Add Variable is enabled.

![Add Variable Dialog](image)

Figure 26: netSCOPE.lvlib:EtherCAT Add or Modify Variable Dialog.vi – Front Panel

- Enter the single variable definition values as described in the table Supported Data Types in EtherCAT on page 75.
### Parameter Description

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Data Flow Area</strong></td>
<td></td>
</tr>
<tr>
<td>Direction</td>
<td>Indicates the signal direction and can either have the value &quot;input&quot; or &quot;output&quot;.</td>
</tr>
<tr>
<td><strong>Datagram Header Area</strong></td>
<td></td>
</tr>
<tr>
<td>Command</td>
<td>This selection specifies the EtherCAT command executed in the EtherCAT datagram. Corresponds to the EtherCAT command specified in the Command field of the EtherCAT datagram. The following EtherCAT commands are defined in the EtherCAT specification:</td>
</tr>
<tr>
<td>Code</td>
<td>Description</td>
</tr>
<tr>
<td>APRD</td>
<td>Auto increment physical read</td>
</tr>
<tr>
<td>APWR</td>
<td>Auto increment physical write</td>
</tr>
<tr>
<td>APRW</td>
<td>Auto increment physical read write</td>
</tr>
<tr>
<td>FPRD</td>
<td>Configured address physical read</td>
</tr>
<tr>
<td>FPWR</td>
<td>Configured address physical write</td>
</tr>
<tr>
<td>FPRW</td>
<td>Configured address physical read write</td>
</tr>
<tr>
<td>BRD</td>
<td>Broadcast read</td>
</tr>
<tr>
<td>BWR</td>
<td>Broadcast write</td>
</tr>
<tr>
<td>BRW</td>
<td>Broadcast read write</td>
</tr>
<tr>
<td>LRD</td>
<td>Logical read</td>
</tr>
<tr>
<td>LWR</td>
<td>Logical write</td>
</tr>
<tr>
<td>LRW</td>
<td>Logical read write</td>
</tr>
<tr>
<td>ARMW</td>
<td>Auto increment physical read multiple write</td>
</tr>
<tr>
<td>FRMW</td>
<td>Configured address physical read multiple write</td>
</tr>
<tr>
<td>Command Address</td>
<td>This value is specified as a hexadecimal address. Corresponds to the address specified in the Command field of the EtherCAT datagram address. The allowed value range extends from 0x0 to 0xFFFFFFFF.</td>
</tr>
<tr>
<td>Datagram Length</td>
<td>Length of the datagram (expressed as the number of bits in the datagram) Corresponds to the length specified in the &quot;Datagram Length&quot; field of the EtherCAT datagram.</td>
</tr>
<tr>
<td>Expected WKC</td>
<td>Expected value of the working counter. Corresponds to the value specified in the field &quot;Expected WKC&quot; of the EtherCAT datagram. The allowed value range extends from 0 to 65535.</td>
</tr>
<tr>
<td><strong>Variable Definition Area</strong></td>
<td></td>
</tr>
<tr>
<td>Variable ID</td>
<td>ID that uniquely identifies the variable. <strong>Note:</strong> You must not use the same variable ID twice otherwise the error message is displayed &quot;Duplicate Variable ID, please select another ID!&quot;</td>
</tr>
<tr>
<td>Data Start Offset (Bits) in Datagram</td>
<td>This value indicates the offset of the variable currently to be defined relative to the beginning of the data field (data) in the EtherCAT datagram. It is expressed as the number of bits counted from the memory location of the first bit of the first variable of the data field. If the variable currently to be defined is the first in the data field, the value is 0.</td>
</tr>
<tr>
<td>Variable Length (Bits)</td>
<td>This value specifies the length of the variable currently to be defined specified as number of the bits.</td>
</tr>
<tr>
<td>Variable Representation</td>
<td>This value specifies the data type of the variable currently to be defined. The following data types are supported in EtherCAT:</td>
</tr>
<tr>
<td>Data Type</td>
<td>Description</td>
</tr>
<tr>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td>BOOLBIT</td>
<td>'0': FALSE '1': TRUE</td>
</tr>
<tr>
<td>BIT8</td>
<td></td>
</tr>
<tr>
<td>SINT</td>
<td>Short integer</td>
</tr>
<tr>
<td>INT</td>
<td>Integer</td>
</tr>
<tr>
<td>Parameter</td>
<td>Description</td>
</tr>
<tr>
<td>-----------</td>
<td>-------------</td>
</tr>
<tr>
<td>INT24</td>
<td>24</td>
</tr>
<tr>
<td>DINT</td>
<td>Double integer</td>
</tr>
<tr>
<td>INT40</td>
<td>40</td>
</tr>
<tr>
<td>INT48</td>
<td>48</td>
</tr>
<tr>
<td>INT56</td>
<td>56</td>
</tr>
<tr>
<td>LINT</td>
<td>Long integer</td>
</tr>
<tr>
<td>USINT</td>
<td>Unsigned short integer</td>
</tr>
<tr>
<td>UINT</td>
<td>Unsigned integer/Word</td>
</tr>
<tr>
<td>UINT24</td>
<td>24</td>
</tr>
<tr>
<td>UDINT</td>
<td>Unsigned double integer</td>
</tr>
<tr>
<td>UINT40</td>
<td>40</td>
</tr>
<tr>
<td>UINT48</td>
<td>48</td>
</tr>
<tr>
<td>UINT56</td>
<td>56</td>
</tr>
<tr>
<td>ULINT</td>
<td>Unsigned long integer</td>
</tr>
<tr>
<td>REAL</td>
<td>Floating point</td>
</tr>
<tr>
<td>LREAL</td>
<td>Long Float</td>
</tr>
<tr>
<td>VISIBLE_STRING</td>
<td>Visible string (1 octet per character)</td>
</tr>
<tr>
<td>OCTET_STRING</td>
<td>Sequence of octets</td>
</tr>
<tr>
<td>UNICODE_STRING</td>
<td>Sequence of UNIT</td>
</tr>
</tbody>
</table>

**Variable Byte Order**

This value indicates the byte order used in the internal representation of the variable currently to be defined.
Possible values are:
- DEC_LITTLE_ENDIAN_BYTE_ORDER (Intel format, which means: the most significant byte comes first, the less significant comes last).
- DEC_BIG_ENDIAN_BYTE_ORDER (Motorola format, which means: the less significant byte comes first, the most significant byte comes last).

**Variable Name**

This value indicates the full name of the variable currently to be defined.

**Note:** You must enter a variable name otherwise the error message is displayed “No variable name specified”.

**Data Normalization Area**

**Normalization Factor**

The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset.
In this field, the normalization factor can be specified.

**Normalization Offset**

The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset.
In this field, the normalization offset can be specified.

---

Table 2: netSCOPE.lvlib: Add or Modify Variable Dialog.vi – Example EtherCAT

- Click on **Add Variable** (below the entry fields).
- The variable definition values for the new variable are stored and the **netSCOPE.lvlib: Add or Modify Variable Dialog.vi** pane is closed.
3.4.2 netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi

The netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi example represents a subfunction of the netSCOPE.lvlib: Interactive Example.vi (see section Open Front Panel, Select Interface, Select Device Frontpanel on page 13) and includes the subfunctions Import variables from ENI, Manually add variable, Edit variable and Show in waveform1.

Figure 27: netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi

- **instrument handle in** identifies a particular instrument session.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in in error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in value to error out**. The **error in** cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the **instrument handle**.
- **selected variable IDs** An array of variable identifiers of all selected variables.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.4.2.1 Open Front Panel, select Variables

In the LabVIEW netSCOPE.lvlib on Main Application Instance / Items pane:

- Select the **Items** tab > netSCOPE.lvlib > Examples > Helpers > EtherCAT.
- Double click to netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi.
- The Front Panel view of the netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi is displayed.
- Click **Run**.
- The netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi is in Run mode:

![Figure 28: netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi](image)

- Select.
- Select the required ENI file (*.xml).
- Select **Import variables from ENI**.
- The imported variables are listed in the **Available Variables** table.
Under **Available Variables** you can remove a variable, clear all variables, add a variable manually or edit a variable.

**Remove selected:**
To remove a variable from the **Available Variables** list:
- Select the variable to be removed.
- Click on **Remove selected**.

**Clear list:**
To clear the total **Available Variables** list:
- Click on **Clear list**.

**Manually add variable:**
To add a variable manually to the **Available Variables** list:
- Click on **Manually add variable**.
- The netSCOPE.lvlib: Add or Modify Variable Dialog.vi pane is displayed.
Enter the single variable definition values as described in the table "Supported Data Types in EtherCAT" on page 75.

Click on Add Variable (below the entry fields).

The variable definition values for the new variable are stored and the netSCOPE.lvlib: Add or Modify Variable Dialog.vi pane is closed.

**Edit variable:**

To edit a variable given in the Available Variables list:

Click on Edit variable.

The netSCOPE.lvlib: Add or Modify Variable Dialog.vi pane is displayed showing the variable definition values of the selected variable.
The single variable definition values as described in the table Supported Data Types in EtherCAT on page 75.

- Edit or change the values.
- Click on Modify Variable (below the entry fields).
- The variable definition values are changes and the netSCOPE.lvlib: Add or Modify Variable Dialog.vi pane is closed.
3.4.2.2 Show in waveform

In the netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi pane put a variable from the Available Variable list by drag & drop to the Show in waveform1 list.

Under Show in waveform1 you can remove a variable and clear all variables.

Remove selected:
To remove a variable from the Show in waveform1 list:
- Select the variable to be removed.
- Click on Remove selected.

Clear list:
To clear the total Show in waveform1 list:
- Click on Clear list.
Done

- Click on **Done**.
- The **netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi** pane is closed.
- The newly defined variables are saved.

### 3.4.2.3 Controls and Indicators in the Frontpanel

![Figure 33: netSCOPE.lvlib: EtherCAT Select Variables Dialog.vi – Controls and Indicators](image)
3.5 Public - Action Status

3.5.1 netSCOPE.lvlib:Get Capture Buffer State.vi

- Gets the current state of the capture ring buffer.

**Figure 34: netSCOPE.lvlib:Get Capture Buffer State.vi**

- **instrument handle in** identifies a particular instrument session.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the **instrument handle**.
- **buffer fill level %** Current ring buffer fill level in percent.
- **current write position %** Current write position of the ring buffer in percent.
- **oldest stored time** Current write position of the ring buffer in percent.
- **newest stored time** Time stamp of the oldest captured and stored datagram in the ring buffer.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.5.2 netSCOPE.lvlib:Get Ethernet Port State.vi

- Gets the state of the Ethernet capture ports of the instrument.

Instrument handle in identifies a particular instrument session.

Error in (no error) describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

- status is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
- source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

Instrument handle out has the same value as the instrument handle.

Ethernet port 0 state Current state information of the netSCOPE instrument on the port 0.

Ethernet link up Current link state of this port.

FALSE: link down
TRUE: link up

Correct frames Total number of successfully received Ethernet frames.

RX_ER errors Total number of faulty received Ethernet frames.

Alignment errors Number of frames with alignment errors (1 additional nibble received)

FCS errors Number of frames with a bad FCS (including short frames with a bad FCS).

Frame length errors Number of frames with invalid Ethernet frame length.

SFD errors Number of Ethernet frames with a SFD (Start of frame delimiter) errors.

Preamble length errors Number of frames with invalid length of preamble.
**Average bus load** Bus load on this port in percent.

**Ethernet speed** Current Ethernet speed 10MBit or 100MBit.

**Ethernet port 1 state** Current state information of the netSCOPE instrument on the port 1.

**Ethernet link up** Current link state of this port. 0: link down 1: link up

**Correct frames** Total number of successfully received Ethernet frames.

**RX_ER errors** Total number of faulty received Ethernet frames.

**Alignment errors** Number of frames with alignment errors (1 additional nibble received)

**FCS errors** Number of frames with a bad FCS (including short frames with a bad FCS).

**Frame length errors** Number of frames with invalid Ethernet frame length.

**SFD errors** Number of Ethernet frames with a SFD (Start of frame delimiter) errors.

**Preamble length errors** Number of frames with invalid length of preamble.

**Average bus load** Bus load on this port in percent.

**Ethernet speed** Current Ethernet speed 10MBit or 100MBit.

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

**code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.

**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.5.3  **netSCOPE.lvlib: Get Instrument State.vi**

- Gets the current state of the instrument.

```
instrument handle in  instrument handle out
error in (no error) bus state
```

**Figure 36: netSCOPE.lvlib: Get Instrument State.vi**

- **instrument handle in** identifies a particular instrument session.
- **instrument handle out** has the same value as the *instrument handle*.
- **bus state** Current bus state of the instrument.
  - Instrument is connected to the bus and ready to capture the data.
  - Instrument is disconnected from the bus (the capturing of the data is no longer possible).
  - Instrument is connected to the bus but stopped because an internal instrument error occurred (the capturing of data is not longer possible).
- **capture state** Current capture state of the instrument.
  - Data capturing is started.
  - Data capturing is stopped.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.5.4 netSCOPE.lvlib:Set Bus Active.vi

- Activates the physical connection to the communication bus or network.
- This is a prerequisite before calling the Start Capture VI.

![Diagram of netSCOPE.lvlib:Set Bus Active.vi](image)

**instrument handle in** identifies a particular instrument session.

**instrument handle out** has the same value as the **instrument handle**.

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

**code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.

**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.5.5 netSCOPE.lvlib:Set Bus Inactive.vi

- Deactivates the physical connection to the communication bus or network.
- If a capture is running it must be stopped via the Stop Capture VI first.

```
instrument handle in   instrument handle out
error in (no error)   error out
```

Figure 38: netSCOPE.lvlib:Set Bus Inactive.vi

- **instrument handle in** identifies a particular instrument session.
- **instrument handle out** has the same value as the **instrument handle**.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.5.6 netSCOPE.lvlib:Start Capture.vi

- Starts the capture task for process data values.
- This requires the bus to be activated via the Set Bus Active VI.

```
instrument handle in  instrument handle out
error in (no error)    error out
```

Figure 39: netSCOPE.lvlib:Start Capture.vi

- **instrument handle in** identifies a particular instrument session.
- **instrument handle out** has the same value as the instrument handle.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.5.7 netSCOPE.lvlib:Stop Capture.vi

- Stops the capture task for process data values.
- After stopping no new data will be stored in the capture ring buffer, but yet captured data is still available.

```
instrument handle in  instrument handle out

error in (no error)    error out
```

*Figure 40: netSCOPE.lvlib:Stop Capture.vi*

- **instrument handle in** identifies a particular instrument session.
- **instrument handle out** has the same value as the **instrument handle**.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.6 Public - Configure - EtherCAT

3.6.1 netSCOPE.lvlib:EtherCAT Configure Detection.vi

- Configures how the EtherCAT direction detection for input / output data works.
- It can be set either to automatic detection or to a user specified fixed configuration.

```
instrument handle in
EtherCAT direction detection
error in (no error)
instrument handle out
```

*Figure 41: netSCOPE.lvlib:EtherCAT Configure Detection.vi*

- **instrument handle in** identifies a particular instrument session.
- **EtherCAT direction detection** Specified EtherCAT direction of input/output data.
  - Port 0 input / Port 1 output
  - Port 0 output / Port 1 input
  - Automatic
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the instrument handle.
- **error out** contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.7 Public – Configure

3.7.1 netSCOPE.lvlib:Register Notification Event Handler.vi

- Registers an user event which will be issued every time a status or error notification is generated by an instrument (see section Notification Events on page 56).

![Diagram](image)

Figure 42: netSCOPE.lvlib:Register Notification Event Handler.vi

- **instrument handle in** identifies a particular instrument session.
- **user event** User event handle that allows receiving the notification events from the backend. This user event is generated by the LabVIEW specific “Create User Event.vi”.
- **notification event entry** Notification event structure. This structure should be specified when creating the user.
  - **Time Stamp** Timestamp of the notification event.
  - **Event** Notification event identifier.
  - **Additional Information** Additional information notification event dependent.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the instrument handle.
- **error out** contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.
- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
**Table 3: Important Error Codes, possible Causes and Troubleshooting**

<table>
<thead>
<tr>
<th>Notification Event</th>
<th>Additional Information</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Instrument connected to bus</td>
<td></td>
<td>The instrument was successfully connected on the bus and is ready to capture of data.</td>
</tr>
<tr>
<td>Instrument connected to bus but stopped by error</td>
<td>Instrument Error: 0xffffffff</td>
<td>The capture of data was automatically stopped because an internal instrument error occurred. Use &quot;Set Bus Inactive.vi&quot; to disconnect the instrument from the bus.</td>
</tr>
<tr>
<td>Instrument disconnected from bus</td>
<td></td>
<td>The instrument was successfully disconnected from bus. Capturing of data is not longer possible.</td>
</tr>
<tr>
<td>Instrument access failed</td>
<td>Instrument Error: 0xffffffff</td>
<td>Access to internal instrument functionality failed. The instrument specific error code is transmitted in &quot;Additional Information&quot; field. Detailed description of error codes see in the netSCOPE documentation.</td>
</tr>
<tr>
<td>License for this product is not activated</td>
<td></td>
<td>The license for this product is not activated. The capturing of data was automatically stopped.</td>
</tr>
<tr>
<td>Ringbuffer out of memory</td>
<td></td>
<td>Internal backend module &quot;Ringbuffer&quot; reports no free system memory.</td>
</tr>
<tr>
<td>Ecat out of memory</td>
<td></td>
<td>Internal backend module &quot;EtherCAT Decoder&quot; reports</td>
</tr>
<tr>
<td>Incompatible data type</td>
<td></td>
<td>The data type of read data is incompatible to defined data types in LabVIEW. The execution of &quot;Read Data.vi&quot; is broken.</td>
</tr>
</tbody>
</table>
### 3.7.2 netSCOPE.lvlib:Ringbuffer Configuration.vi

- Configures the ringbuffer storage size in Megabytes and location.
- RAM storage location does not need a save path.
- HDD storage location needs a save path to be specified.

Note, that HDD storage is most likely less performant than RAM storage.

#### Figure 43: netSCOPE.lvlib:Ringbuffer Configuration.vi

- **ringbuffer save path** Path of the ring buffer location on the HDD.
- **instrument handle in** identifies a particular instrument session.
- **ringbuffer size [MByte]** Size of the ring buffer.
- **ringbuffer save location (RAM)** Specifies where the ring buffer should be created RAM / HDD.

**error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in in error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

- **instrument handle out** has the same value as the **instrument handle**.

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.7.3  netSCOPE.lvlib:Unregister Notification Event Handler.vi

- Unregisters the instruments notification user event handler. No more user events will be issued.

```
instrument handle in          instrument handle out
error in (no error)           error out
```

*Figure 44: netSCOPE.lvlib:Unregister Notification Event Handler.vi*

- `instrument handle in` identifies a particular instrument session.
- `instrument handle out` has the same value as the `instrument handle`.
- `error out` contains error information. If `error in` indicates that an error occurred before this VI or function ran, `error out` contains the same error information. Otherwise, it describes the error status that this VI or function produces.

- `status` is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

- `code` is the error or warning code. The default is 0. If `status` is TRUE, `code` is a negative error code. If `status` is FALSE, `code` is 0 or a warning code.

- `source` identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.8 Public - Data

3.8.1 netSCOPE.lvlib:Read Data.vi

- Reads a variables values from the capture data ring buffer.
- Reading is limited to the time span given, ‘read from timestamp’ must always be specified.
- The maximum amount of data that is read out is implicitly specified by the input arrays size.
- All input arrays (timestamp list, value list, status list) must have the same size.
- The value list contains elements which must be preinitialized with the LabVIEW data type and its expected size.
- The amount of actually read values is returned by "count of read values", if this value is smaller than the array size, the rest of the arrays elements do not contain correct data and must be ignored. The VI does not resize the arrays automatically.

![Diagram of netSCOPE.lvlib:Read Data.vi](image)

Figure 45: netSCOPE.lvlib:Read Data.vi

![Diagram of Variable Data Management](image)

Figure 46: Variable Data Management

- **read to timestamp** Timestamp where the reading process should be aborted.
- **read from timestamp** Timestamp where the reading process should be started.
- **instrument handle in** identifies a particular instrument session.
- **variable ID** Identifier of the variable that should be read from the ring buffer.
Variable ID Value Value of the variable ID.

Instance Handle Internal driver information.

timestamp list in Timestamp array with pre-initialized size.

value list in Value array with pre-initialized size. The data type of this array should match the expected value data type.

status list in State array with pre-initialized size.

error in (no error) describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

status is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

instrument handle out has the same value as the instrument handle.

count of read values Counter that indicates how many values were read from the ringbuffer (relevant for timestamp list out, value list out and status list out arrays).

timestamp list out Array of read timestamps.

value list out Array of read values.

status list out Array of read value states.

error out contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.

status is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

more data Indicates if reading values has been completed in the specified time span (reading from timestamp - reading to timestamp). - True: Reading the data has not been completed because the size of pre-initialized arrays (timestamp list in, value list in and status list in)
was not sufficient.
- False: Reading the data has been completed.
3.9 Public - Utility - EtherCAT

3.9.1 netSCOPE.lvlib:EtherCAT Add or Modify Variable.vi

- Adds or modifies the EtherCAT-specific definition of the given variable.
- EtherCAT-specific VI.

```plaintext
instrument handle in
 EtherCAT variable definition
   error in (no error)
```

Figure 47: netSCOPE.lvlib:EtherCAT Add or Modify Variable.vi

- `instrument handle in` identifies a particular instrument session.
- `instrument handle out` has the same value as the `instrument handle`.
- `EtherCAT variable definition` Cluster of specific EtherCAT variable definition.

Figure 48: EtherCAT Datagram and Variable Definition

- `Command` (Datagram Header Area) This selection specifies the EtherCAT command executed in the EtherCAT datagram. Corresponds to the EtherCAT command specified in the Command field of the EtherCAT datagram.
The following EtherCAT commands are defined in the EtherCAT specification:

<table>
<thead>
<tr>
<th>Code</th>
<th>Command</th>
</tr>
</thead>
<tbody>
<tr>
<td>APRD</td>
<td>Auto increment physical read</td>
</tr>
<tr>
<td>APWR</td>
<td>Auto increment physical write</td>
</tr>
<tr>
<td>APRW</td>
<td>Auto increment physical read write</td>
</tr>
<tr>
<td>FPRD</td>
<td>Configured address physical read</td>
</tr>
<tr>
<td>FPWR</td>
<td>Configured address physical write</td>
</tr>
<tr>
<td>FPRW</td>
<td>Configured address physical read write</td>
</tr>
<tr>
<td>BRD</td>
<td>Broadcast read</td>
</tr>
<tr>
<td>BWR</td>
<td>Broadcast write</td>
</tr>
<tr>
<td>BRW</td>
<td>Broadcast read write</td>
</tr>
<tr>
<td>LRD</td>
<td>Logical read</td>
</tr>
<tr>
<td>LWR</td>
<td>Logical write</td>
</tr>
<tr>
<td>LRW</td>
<td>Logical read write</td>
</tr>
<tr>
<td>ARMW</td>
<td>Auto increment physical read multiple write</td>
</tr>
<tr>
<td>FRMW</td>
<td>Configured address physical read multiple write</td>
</tr>
</tbody>
</table>

Table 4: EtherCAT Commands

- **Command Address (Datagram Header Area)** This value is specified as a hexadecimal address. Corresponds to the address specified in the Command field of the EtherCAT datagram address. The allowed value range extends from 0x0 to 0xFFFFFFFF.

- **Working Counter (Datagram Header Area)** Expected value of the working counter. Corresponds to the value specified in the field "Expected WKC" of the EtherCAT datagram. The allowed value range extends from 0 to 65535.

- **Command Length (Datagram Header Area)** Length of the datagram (expressed as the number of bits in the datagram). Corresponds to the length specified in the "Datagram Length" field of the EtherCAT datagram.

- **Variable Bit-Address (Variable Definition Area - Data Start Offset (Bits) in Datagram)** This value indicates the offset of the variable currently to be defined relative to the beginning of the data field (data) in the EtherCAT datagram. It is expressed as the number of bits counted from the memory location of the first bit of the first variable of the data field. If the variable currently to be defined is the first in the data field, the value is 0.

- **Generic Variable Definition** Cluster of generic variable definition.

- **Variable Data Type (Variable Definition Area)** This value specifies the data type of the variable currently to be defined. The following data types are supported in EtherCAT:

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Description</th>
<th>Number of Bits</th>
<th>Range of Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOOLBIT</td>
<td>‘0’: FALSE</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>‘1’: TRUE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BIT8</td>
<td></td>
<td>8</td>
<td>-128 … 127</td>
</tr>
<tr>
<td>SINT</td>
<td>Short integer</td>
<td>8</td>
<td>-128 … 127</td>
</tr>
<tr>
<td>Data Type</td>
<td>Description</td>
<td>Number of Bits</td>
<td>Range of Value</td>
</tr>
<tr>
<td>-----------</td>
<td>----------------------</td>
<td>----------------</td>
<td>--------------------</td>
</tr>
<tr>
<td>INT</td>
<td>Integer</td>
<td>16</td>
<td>-32768 ... 32767</td>
</tr>
<tr>
<td>INT24</td>
<td></td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>DINT</td>
<td>Double integer</td>
<td>32</td>
<td>-231 ... +231-1</td>
</tr>
<tr>
<td>INT40</td>
<td></td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>INT48</td>
<td></td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>INT56</td>
<td></td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>LINT</td>
<td>Long integer</td>
<td>64</td>
<td></td>
</tr>
<tr>
<td>USINT</td>
<td>Unsigned short integer</td>
<td>8</td>
<td>0 ... 255</td>
</tr>
<tr>
<td>UINT</td>
<td>Unsigned integer/Word</td>
<td>16</td>
<td>0 ... 65535</td>
</tr>
<tr>
<td>UINT24</td>
<td></td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>UDINT</td>
<td>Unsigned double integer</td>
<td>32</td>
<td>0 ... +232-1</td>
</tr>
<tr>
<td>UINT40</td>
<td></td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>UINT48</td>
<td></td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>UINT56</td>
<td></td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>ULINT</td>
<td>Unsigned long integer</td>
<td>64</td>
<td>0 ... +264-1</td>
</tr>
<tr>
<td>REAL</td>
<td>Floating point</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>LREAL</td>
<td>Long Float</td>
<td>64</td>
<td></td>
</tr>
<tr>
<td>VISIBLE_STRING</td>
<td>Visible string</td>
<td>8*n</td>
<td></td>
</tr>
<tr>
<td>OCTET_STRING</td>
<td>Sequence of octets</td>
<td>8*(n+1)</td>
<td></td>
</tr>
<tr>
<td>UNICODE_STRING</td>
<td>Sequence of UNIT</td>
<td>16*(n+1)</td>
<td></td>
</tr>
</tbody>
</table>

Table 5: Supported Data Types in EtherCAT

- **Variable Direction** (Data Flow Area) Indicates the signal direction and can either have the value "input" or "output".

- **Variable Byte Order** (Variable Definition Area) This value indicates the byte order used in the internal representation of the variable currently to be defined. Possible values are: **DEC_LITTLE_ENDIAN_BYTE_ORDER** (Intel format, which means: the most significant byte comes first, the less significant comes last). **DEC_BIG_ENDIAN_BYTE_ORDER** (Motorola format, which means: the less significant byte comes first, the most significant byte comes last).

- **Name** (Variable Definition Area) This value indicates the full name of the variable currently to be defined.

- **Normalization Slope** (Data Normalization Area) The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset. In this field, the normalization factor can be specified.

- **Normalization Offset** (Data Normalization Area) The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset. In this field, the normalization offset can be specified.

- **Variable ID** (Variable Definition Area) ID that uniquely identifies the variable.

- **Variable ID Value** Value of the variable ID.
Instance Handle  Internal driver information.

Scaling active  ‘Normalization Slope’ and ‘Normalization Offset’ and are only considered when ‘Scaling active’ is TRUE.

Variable Bit-Length  (Variable Definition Area) This value specifies the length of the variable currently to be defined specified as number of the bits.

error in (no error)  describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

status  is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code  is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source  identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

instrument handle out  has the same value as the instrument handle.

error out  contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.

status  is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code  is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source  identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.9.2 netSCOPE.lvlib:EtherCAT Get Specific Variable Definition.vi

- Gets the EtherCAT-specific definition of a variable.
- EtherCAT-specific VI.

![Diagram](image)

**Figure 49: netSCOPE.lvlib:EtherCAT Get Specific Variable Definition.vi**

**instrument handle in** identifies a particular instrument session.

**variable ID** Variable identifier.

**Variable ID Value** Value of the variable ID.

**Instance Handle** Internal driver information.

**error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in in error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in value to error out**. The **error in** cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

**EtherCAT variable definition** Cluster of specific EtherCAT variable definition.
Figure 50: EtherCAT Datagram and Variable Definition

**Command** (Datagram Header Area) This selection specifies the EtherCAT command executed in the EtherCAT datagram. Corresponds to the EtherCAT command specified in the Command field of the EtherCAT datagram. The following EtherCAT commands are defined in the EtherCAT specification:

<table>
<thead>
<tr>
<th>Code</th>
<th>Command</th>
</tr>
</thead>
<tbody>
<tr>
<td>APRD</td>
<td>Auto increment physical read</td>
</tr>
<tr>
<td>APWR</td>
<td>Auto increment physical write</td>
</tr>
<tr>
<td>APRW</td>
<td>Auto increment physical read write</td>
</tr>
<tr>
<td>FPRD</td>
<td>Configured address physical read</td>
</tr>
<tr>
<td>FPWR</td>
<td>Configured address physical write</td>
</tr>
<tr>
<td>FPRW</td>
<td>Configured address physical read write</td>
</tr>
<tr>
<td>BRD</td>
<td>Broadcast read</td>
</tr>
<tr>
<td>BWR</td>
<td>Broadcast write</td>
</tr>
<tr>
<td>BRW</td>
<td>Broadcast read write</td>
</tr>
<tr>
<td>LRD</td>
<td>Logical read</td>
</tr>
<tr>
<td>LWR</td>
<td>Logical write</td>
</tr>
<tr>
<td>LRW</td>
<td>Logical read write</td>
</tr>
<tr>
<td>ARMW</td>
<td>Auto increment physical read multiple write</td>
</tr>
<tr>
<td>Code</td>
<td>Command</td>
</tr>
<tr>
<td>--------</td>
<td>----------------------------------------------</td>
</tr>
<tr>
<td>FRMW</td>
<td>Configured address physical read multiple write</td>
</tr>
</tbody>
</table>

**Table 6: EtherCAT Commands**

- **Command Address** (Datagram Header Area) This value is specified as a hexadecimal address. Corresponds to the address specified in the Command field of the EtherCAT datagram address. The allowed value range extends from 0x0 to 0xFFFFFFFF.

- **Working Counter** (Datagram Header Area) Expected value of the working counter. Corresponds to the value specified in the field "Expected WKC" of the EtherCAT datagram. The allowed value range extends from 0 to 65535.

- **Command Length** (Datagram Header Area) Length of the datagram (expressed as the number of bits in the datagram). Corresponds to the length specified in the "Datagram Length" field of the EtherCAT datagram.

- **Variable Bit-Address** (Variable Definition Area - Data Start Offset (Bits) in Datagram) This value indicates the offset of the variable currently to be defined relative to the beginning of the data field (data) in the EtherCAT datagram. It is expressed as the number of bits counted from the memory location of the first bit of the first variable of the data field. If the variable currently to be defined is the first in the data field, the value is 0.

- **Generic Variable Definition** Cluster of generic variable definition.

- **Variable Data Type** (Variable Definition Area) This value specifies the data type of the variable currently to be defined. The following data types are supported in EtherCAT:

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Description</th>
<th>Number of Bits</th>
<th>Range of Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOOLBIT</td>
<td>'0': FALSE '1': TRUE</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>BIT8</td>
<td></td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>SINT</td>
<td>Short integer</td>
<td>8</td>
<td>-128 … 127</td>
</tr>
<tr>
<td>INT</td>
<td>Integer</td>
<td>16</td>
<td>-32768 … 32767</td>
</tr>
<tr>
<td>INT24</td>
<td></td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>DINT</td>
<td>Double integer</td>
<td>32</td>
<td>-231 … +231-1</td>
</tr>
<tr>
<td>INT40</td>
<td></td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>INT48</td>
<td></td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>INT56</td>
<td></td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>LINT</td>
<td>Long integer</td>
<td>64</td>
<td></td>
</tr>
<tr>
<td>USINT</td>
<td>Unsigned short integer</td>
<td>8</td>
<td>0 … 255</td>
</tr>
<tr>
<td>UINT</td>
<td>Unsigned integer/Word</td>
<td>16</td>
<td>0 … 65535</td>
</tr>
<tr>
<td>UINT24</td>
<td></td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>UDINT</td>
<td>Unsigned double integer</td>
<td>32</td>
<td>0 … 232-1</td>
</tr>
<tr>
<td>UINT40</td>
<td></td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>UINT48</td>
<td></td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>UINT56</td>
<td></td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>ULINT</td>
<td>Unsigned long integer</td>
<td>64</td>
<td>0 … 264-1</td>
</tr>
</tbody>
</table>
### Table 7: Supported Data Types in EtherCAT

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Description</th>
<th>Number of Bits</th>
<th>Range of Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>REAL</td>
<td>Floating point</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>LREAL</td>
<td>Long Float</td>
<td>64</td>
<td></td>
</tr>
<tr>
<td>VISIBLE_STRING</td>
<td>Visible string (1 octet per character)</td>
<td>8*n</td>
<td></td>
</tr>
<tr>
<td>OCTET_STRING</td>
<td>Sequence of octets</td>
<td>8*(n+1)</td>
<td></td>
</tr>
<tr>
<td>UNICODE_STRING</td>
<td>Sequence of UNIT</td>
<td>16*(n+1)</td>
<td></td>
</tr>
</tbody>
</table>

**Variable Direction** (Data Flow Area) Indicates the signal direction and can either have the value "input" or "output".

**Variable Byte Order** (Variable Definition Area) This value indicates the byte order used in the internal representation of the variable currently to be defined. Possible values are:
- DEC_LITTLE_ENDIAN_BYTE_ORDER (Intel format, which means: the most significant byte comes first, the less significant comes last).
- DEC_BIG_ENDIAN_BYTE_ORDER (Motorola format, which means: the less significant byte comes first, the most significant byte comes last).

**Name** (Variable Definition Area) This value indicates the full name of the variable currently to be defined.

**Normalization Slope** (Data Normalization Area) The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset. In this field, the normalization factor can be specified.

**Normalization Offset** (Data Normalization Area) The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset. In this field, the normalization offset can be specified.

**Variable ID** (Variable Definition Area) ID that uniquely identifies the variable.

**Variable ID Value** Value of the variable ID.

**Instance Handle** Internal driver information.

**Scaling active** 'Normalization Slope' and 'Normalization Offset' and are only considered when 'Scaling active' is TRUE.

**Variable Bit-Length** (Variable Definition Area) This value specifies the length of the variable currently to be defined specified as number of the bits.

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.9.3 netSCOPE.lvlib:EtherCAT Load ENI File.vi

- Loads all variables from the given ENI file.
- EtherCAT-specific VI.

```
instrument handle in  instrument handle out
ENI file path  
error in (no error)  error out
```

**Figure 51: netSCOPE.lvlib:EtherCAT Load ENI File.vi**

- **instrument handle in** identifies a particular instrument session.
- **ENI file path** Path to the EtherCAT specific ENI file.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:

  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

- **instrument handle out** has the same value as the **instrument handle**.

- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.10 Public - Utility

3.10.1 netSCOPE.lvlib:Error Descriptions.vi

- This VI returns all netSCOPE-specific error codes and descriptions.
- Useful to be connected to the General Error Handler VIs [user-defined codes] and [user-defined descriptions] inputs.

![Diagram of netSCOPE.lvlib:Error Descriptions.vi]

Figure 52: netSCOPE.lvlib:Error Descriptions.vi

- **error descriptions** Error code.
- **error codes** Error short description.
3.10.2 netSCOPE.lvlib:Get Generic Variable Definition.vi

- Gets the generic, system-independent definition of a variable.

![Diagram](image)

Figure 53: netSCOPE.lvlib:Get Generic Variable Definition.vi

- **instrument handle in** identifies a particular instrument session.
- **variable ID** Variable identifier.
- **Variable ID Value** Value of the variable ID.
- **Instance Handle** Internal driver information.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the **instrument handle**.
- **generic variable definition** Cluster of generic variable definition.
- **Variable Data Type** (Variable Definition Area) This value specifies the data type of the variable currently to be defined. The following data types are supported in EtherCAT:

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Description</th>
<th>Number of Bits</th>
<th>Range of Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOOLBIT</td>
<td>’0’: FALSE</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>’1’: TRUE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BIT8</td>
<td></td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>SINT</td>
<td>Short integer</td>
<td>8</td>
<td>-128 … 127</td>
</tr>
<tr>
<td>INT</td>
<td>Integer</td>
<td>16</td>
<td>-32768 … 32767</td>
</tr>
<tr>
<td>INT24</td>
<td></td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>DINT</td>
<td>Double integer</td>
<td>32</td>
<td>-231 … +231-1</td>
</tr>
<tr>
<td>INT40</td>
<td></td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>INT48</td>
<td></td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>INT56</td>
<td></td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>LINT</td>
<td>Long integer</td>
<td>64</td>
<td></td>
</tr>
<tr>
<td>USINT</td>
<td>Unsigned short integer</td>
<td>8</td>
<td>0 … 255</td>
</tr>
</tbody>
</table>
### Table 8: Supported Data Types in EtherCAT

<table>
<thead>
<tr>
<th>Data Type</th>
<th>Description</th>
<th>Number of Bits</th>
<th>Range of Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>UINT</td>
<td>Unsigned integer/Word</td>
<td>16</td>
<td>0 … 65535</td>
</tr>
<tr>
<td>UINT24</td>
<td></td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>UDINT</td>
<td>Unsigned double integer</td>
<td>32</td>
<td>0 … +232-1</td>
</tr>
<tr>
<td>UINT40</td>
<td></td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>UINT48</td>
<td></td>
<td>48</td>
<td></td>
</tr>
<tr>
<td>UINT56</td>
<td></td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>ULINT</td>
<td>Unsigned long integer</td>
<td>64</td>
<td>0 … +264-1</td>
</tr>
<tr>
<td>REAL</td>
<td>Floating point</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>LREAL</td>
<td>Long Float</td>
<td>64</td>
<td></td>
</tr>
<tr>
<td>VISIBLE_STRING</td>
<td>Visible string</td>
<td>8*n</td>
<td></td>
</tr>
<tr>
<td>OCTET_STRING</td>
<td>Sequence of octets</td>
<td>8*(n+1)</td>
<td></td>
</tr>
<tr>
<td>UNICODE STRING</td>
<td>Sequence of UNIT</td>
<td>16*(n+1)</td>
<td></td>
</tr>
</tbody>
</table>

- **Variable Direction** (Data Flow Area) Indicates the signal direction and can either have the value "input" or "output".
- **Variable Byte Order** (Variable Definition Area) This value indicates the byte order used in the internal representation of the variable currently to be defined. Possible values are:
  - DEC_LITTLE_ENDIAN_BYTE_ORDER
    (Intel format, which means: the most significant byte comes first, the less significant comes last).
  - DEC_BIG_ENDIAN_BYTE_ORDER
    (Motorola format, which means: the less significant byte comes first, the most significant byte comes last).
- **Name** (Variable Definition Area) This value indicates the full name of the variable currently to be defined.
- **Normalization Slope** (Data Normalization Area) The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset. In this field, the normalization factor can be specified.
- **Normalization Offset** (Data Normalization Area) The data can be normalized if necessary by multiplication by a normalization factor and adding a normalization offset. In this field, the normalization offset can be specified.
- **Variable ID** (Variable Definition Area) ID that uniquely identifies the variable.
- **Variable ID Value** Value of the variable ID.
- **Instance Handle** Internal driver information.
- **Scaling active** 'Normalization Slope’ and ‘Normalization Offset’ and are only considered when ‘Scaling active’ is TRUE.
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

**code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.

**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.10.3 *netSCOPE.lvlib:Get Instrument List.vi*

- Returns a list of all instruments of the system.

  ![Diagram](image.png)

  Figure 54: netSCOPE.lvlib:Get Instrument List.vi

**system handle in** Valid system handle generated by “Initialize System.vi” (see section *netSCOPE.lvlib:Initialize System.vi* page 86).

**error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

**system handle out** Valid system handle generated by “Initialize System.vi” (see section *netSCOPE.lvlib:Initialize System.vi* page 86).

**instruments list** A list of available instruments found on the system.

**instruments list** Structure with device information.

- **Instruments list** Device number of the instrument.
  - Device number
    - 7330100 NSCP-C100-RE\50
    - 7330101 NSCP-C100-RE\50E
    - 7330102 NSCP-C100-RE\70E
    - 7330103 NSCP-C100-RE\80
    - 7330105 NSCP-C100-RE\90E
  - **Serial number** Serial number of the instrument.
  - **Device Class** Device class of the instrument.
  - **Name** Instrument name.

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
**code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.

**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.10.4 netSCOPE.lvlib:Get Variable IDs by Name.vi

- Returns a list of variables IDs for all variables which's name matches the given regular expression.

\[\text{instrument handle in} \rightarrow \text{variable ID list} \rightarrow \text{error out}\]

Figure 55:  netSCOPE.lvlib:Get Variable IDs by Name.vi

- **instrument handle in** identifies a particular instrument session.
- **regular expression (.*)** Variable name.
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
- **instrument handle out** has the same value as the instrument handle.
- **variable ID list** An array of variable identifiers that match the given variable name.
- **variable ID** Identifier of the variable that should be read from the ring buffer.
- **Variable ID Value** Value of the variable ID.
- **Instance Handle** Internal driver information.
- **error out** contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.
  - **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
  - **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
  - **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.10.5 netSCOPE.lvlib:Identify.vi

- Blinks the given instruments LEDs for identification.

![Diagram](Figure 56: netSCOPE.lvlib:Identify.vi)

**system handle in** Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).

**instrument name** Instrument name (for example „netSCOPE0”). The instrument name can be extracted from the instrument list generated by “Get Instrument List.vi” (see section netSCOPE.lvlib:Get Instrument List.vi page 77).

**error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in in error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:

**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

**code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.

**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

**system handle out** Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

**status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

**code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.

**source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.10.6  netSCOPE.lvlib:Remove Variable.vi

- Removes a variable definition from the list of known variables.
- If the variable is removed its values may not be read out anymore by the Get Data VI.

Figure 57:  netSCOPE.lvlib:Remove Variable.vi

instrument handle in  instrument handle out
variable ID  Variable ID Value
error in (no error)  error out

instrument handle in identifies a particular instrument session.
variable ID Identifier of the variable that should be removed from the known variables list.
Variable ID Value Value of the variable ID.
Instance Handle Internal driver information.
error in (no error) describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

status is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

instrument handle out has the same value as the instrument handle.
error out contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.

status is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.10.7 netSCOPE.lvlib:Revision Query.vi

- Queries version information of all netSCOPE software and hardware modules.

**Figure 58: netSCOPE.lvlib:Revision Query.vi**

**error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

**revision info** Includes version information of individual system components (driver version, ringbuffer version, ...).

**Revision Info Entry** Structure with version information.

- **Component Name** Name of the component.
- **Component Details** Version information.

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.11 Public

3.11.1 netSCOPE.lvlib:Close Instrument.vi

- Closes an instrument and returns the system handle the instrument belongs to.
- This will discard all configuration and captured ring buffer data for this instrument.
- The Instrument will not be accessible anymore unless it is reopened via the Initialize Instrument VI.

```plaintext
instrument handle --------> system handle

error in (no error) --------> error out

Figure 59: netSCOPE.lvlib:Close Instrument.vi
```

- **instrument handle in** identifies a particular instrument session.
- **system handle in** Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).
- **error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.
- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.11.2 netSCOPE.lvlib:Close System.vi

- Closes a system.
- All instruments belonging to this system will be closed automatically, all captured ringbuffer data in this system will be discarded.

```
system handle
error in (no error)
```

Figure 60: netSCOPE.lvlib:Close System.vi

- **system handle** in Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).
- **error in (no error)** describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

- **error out** contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.11.3 netSCOPE.lvlib:Initialize Instrument.vi

- Initialize one instrument specified by its name.
- This VI must be called once before using any instrument specific VIs.

Figure 61: netSCOPE.lvlib:Initialize Instrument.vi

system handle in  Valid system handle generated by "Initialize System.vi" (see section netSCOPE.lvlib:Initialize System.vi page 86).

system ID  Target system identifier.

instrument name  Name of the instrument that should be initialized.

error in (no error)  describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of error in in error out. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the error in value to error out. The error in cluster contains the following parameters:

status  is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code  is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source  identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

instrument handle out  has the same value as the instrument handle.

error out  contains error information. If error in indicates that an error occurred before this VI or function ran, error out contains the same error information. Otherwise, it describes the error status that this VI or function produces.

status  is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.

code  is the error or warning code. The default is 0. If status is TRUE, code is a negative error code. If status is FALSE, code is 0 or a warning code.

source  identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
3.11.4 netSCOPE.lvlib:Initialize System.vi

- Initialized the netSCOPE system.
- This is the first VI to be called before any other netSCOPE VI is useable.

![System handle](image)

Figure 62: netSCOPE.lvlib:Initialize System.vi

**error in** (no error) describes error conditions that occur before this VI runs. The default input of this cluster is no error. If an error already occurred, this VI returns the value of **error in** in **error out**. The VI runs normally only if no incoming error exists. Otherwise, the VI passes the **error in** value to **error out**. The **error in** cluster contains the following parameters:

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.

**system handle** in Valid system handle generated by “Initialize System.vi” (see section netSCOPE.lvlib:Initialize System.vi page 86).

**error out** contains error information. If **error in** indicates that an error occurred before this VI or function ran, **error out** contains the same error information. Otherwise, it describes the error status that this VI or function produces.

- **status** is TRUE (X) if an error occurred before this VI or function ran or FALSE (checkmark) to indicate a warning or that no error occurred before this VI or function ran. The default is FALSE.
- **code** is the error or warning code. The default is 0. If **status** is TRUE, **code** is a negative error code. If **status** is FALSE, **code** is 0 or a warning code.
- **source** identifies where an error occurred. The source string includes the name of the VI that produced the error, what inputs are in error, and how to eliminate the error.
4 Error Codes

4.1 Overview Error Codes

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<tr>
<th>Error Codes</th>
<th>Type</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
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<td>Errors</td>
<td>5000 … 5305</td>
</tr>
<tr>
<td>netANALYZER / netSCOPE Windows Device Driver Errors [1]</td>
<td>Generic Errors</td>
<td>Warnings</td>
</tr>
<tr>
<td></td>
<td>Toolkit Errors</td>
<td>Warnings</td>
</tr>
<tr>
<td></td>
<td>Driver Errors</td>
<td>Warnings</td>
</tr>
<tr>
<td>Capturing Errors</td>
<td>Errors</td>
<td>0x00000000 … 0xC0770000</td>
</tr>
</tbody>
</table>

Table 9: Overview Error Codes and Ranges

4.2 LabVIEW Errors Description

<table>
<thead>
<tr>
<th>Value</th>
<th>Error Code (Definition)</th>
<th>Short Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>5000</td>
<td>Duplicate variable ID</td>
<td>During manual configuration of variable was assigned a duplicate variable ID.</td>
</tr>
<tr>
<td>5001</td>
<td>Instrument not opened</td>
<td>No instrument initialized (&quot;Open Instrument.vi&quot; wasn't executed or during the execution failed).</td>
</tr>
<tr>
<td>5002</td>
<td>Instance mismatch</td>
<td>Wrong instrument instance.</td>
</tr>
<tr>
<td>5003</td>
<td>Target system not supported</td>
<td>The selected target system isn't supported of netSCOPE.</td>
</tr>
<tr>
<td>5004</td>
<td>Error loading backend DLLs</td>
<td>Loading of internal DLL components is failed.</td>
</tr>
<tr>
<td>5005</td>
<td>Error loading file</td>
<td>Loading of ENI file is failed. Invalid path was specified or imported file has incorrect format.</td>
</tr>
<tr>
<td>5006</td>
<td>Variable ID not found</td>
<td>The variable with the specified ID wasn't found in variable list.</td>
</tr>
<tr>
<td>5007</td>
<td>Array sizes don't match</td>
<td>The size of timestamp-, data- and valid-array don't match.</td>
</tr>
<tr>
<td>5008</td>
<td>Incompatible data type</td>
<td>The variable data type don't match with defined LabVIEW data types (see &quot;Variable Data Type.ctl&quot;).</td>
</tr>
<tr>
<td>5009</td>
<td>Out of memory</td>
<td>No more free system memory available.</td>
</tr>
<tr>
<td>5010</td>
<td>Unknown interface command</td>
<td>Unknown backend interface command.</td>
</tr>
<tr>
<td>5011</td>
<td>Invalid instance handle</td>
<td>Invalid instance handle = 0x00000000. (&quot;Open Instrument.vi&quot; wasn’t executed or during the execution failed).</td>
</tr>
<tr>
<td>5012</td>
<td>System not initialized</td>
<td>System not initialized (&quot;Initialize System.vi&quot; wasn’t executed or during the execution failed).</td>
</tr>
<tr>
<td>5014</td>
<td>Invalid parameter</td>
<td>Invalid parameter in the calling VI.</td>
</tr>
<tr>
<td>5100</td>
<td>Instrument access failed</td>
<td>Access to internal instrument functionality is failed. It triggers a notification event which contains a detailed description of this error.</td>
</tr>
<tr>
<td>5101</td>
<td>Instrument invalid parameter</td>
<td>Wrong configuration parameter. (internal instrument error)</td>
</tr>
<tr>
<td>5102</td>
<td>Instrument not found</td>
<td>Instrument with passed name wasn't found. (internal instrument error)</td>
</tr>
<tr>
<td>5103</td>
<td>Instrument IOCTL failed</td>
<td>General error at sending of IOCTL. (internal instrument error)</td>
</tr>
<tr>
<td>5200</td>
<td>Ringbuffer failed</td>
<td>Internal ringbuffer module error. (internal instrument error)</td>
</tr>
<tr>
<td>5201</td>
<td>Ringbuffer get time invalid</td>
<td>Invalid read data time span, from time is greater as to time. (internal ringbuffer error)</td>
</tr>
<tr>
<td>5202</td>
<td>Ringbuffer invalid parameter</td>
<td>Access to EtherCAT-Decoder failed because of an invalid transfer parameter. (internal ringbuffer error)</td>
</tr>
<tr>
<td>5203</td>
<td>Ringbuffer out of memory</td>
<td>No more free system memory available. (internal ringbuffer error)</td>
</tr>
</tbody>
</table>
### 4.3 Generic Errors

<table>
<thead>
<tr>
<th>Value</th>
<th>Error Code (Definition)</th>
<th>Description</th>
<th>Possible Causes</th>
<th>Troubleshooting</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x80200003</td>
<td>NETANA_OUT_OF_MEMORY</td>
<td>Out of memory</td>
<td>The available storage capacity of central memory is full.</td>
<td>Upgrade the storage capacity of the central memory. Close all other open applications on the PC.</td>
</tr>
</tbody>
</table>

### 4.4 Toolkit Errors

<table>
<thead>
<tr>
<th>Value</th>
<th>Error Code (Definition)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x80210001</td>
<td>NETANA_TKIT_INITIALIZATION_FAILED</td>
<td>Toolkit initialization failed</td>
</tr>
<tr>
<td>0x80210002</td>
<td>NETANA_DMABUFFER_CREATION_FAILED</td>
<td>Creation of DMA buffers failed</td>
</tr>
<tr>
<td>0x80210003</td>
<td>NETANA_HWRESET_ERROR</td>
<td>Error during hardware reset of device</td>
</tr>
<tr>
<td>0x80210004</td>
<td>NETANA_CHIP_NOT_SUPPORTED</td>
<td>Chip type is not supported by toolkit</td>
</tr>
<tr>
<td>0x80210005</td>
<td>NETANA_DOWNLOAD_FAILED</td>
<td>Download of Bootloader / Firmware failed</td>
</tr>
<tr>
<td>0x80210006</td>
<td>NETANA_FW_START_FAILED</td>
<td>Error starting firmware</td>
</tr>
<tr>
<td>0x80210007</td>
<td>NETANA_DEV_MAILBOX_FULL</td>
<td>Device mailbox is full</td>
</tr>
<tr>
<td>0x80210008</td>
<td>NETANA_DEV_NOT_READY</td>
<td>Device not ready</td>
</tr>
<tr>
<td>0x80210009</td>
<td>NETANA_DEV_MAILBOX_TOO_SHORT</td>
<td>Mailbox is too short for packet</td>
</tr>
<tr>
<td>0x8021000A</td>
<td>NETANA_DEV_GET_NO_PACKET</td>
<td>No packet available</td>
</tr>
<tr>
<td>0x8021000B</td>
<td>NETANA_BUFFER_TOO_SHORT</td>
<td>Given buffer is too short</td>
</tr>
</tbody>
</table>
### Error Codes

<table>
<thead>
<tr>
<th>Value</th>
<th>Error Code (Definition)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x8021000C</td>
<td>NETANA_TRANSFER_TIMEOUT</td>
<td>Transfer timed out</td>
</tr>
<tr>
<td>0x8021000D</td>
<td>NETANA_IRQEVENT_CREATION_FAILED</td>
<td>Error creating interrupt events</td>
</tr>
<tr>
<td>0x8021000E</td>
<td>NETANA_IRQLOCK_CREATION_FAILED</td>
<td>Error creating internal IRQ locks</td>
</tr>
</tbody>
</table>

**Table 12: Toolkit Errors Description**

#### 4.5 Driver Errors

<table>
<thead>
<tr>
<th>Value</th>
<th>Error Code (Definition)</th>
<th>Description</th>
<th>Possible Causes</th>
<th>Troubleshooting</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x80220002</td>
<td>NETANA_DRIVER_NOT_RUNNING</td>
<td>netANALYZER / netSCOPE Windows Device Driver is not running</td>
<td>The netANALYZER / netSCOPE Windows Device Driver is not installed.</td>
<td>Install the netANALYZER / netSCOPE Windows Device Driver.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The netANALYZER / netSCOPE Windows Device Driver is installed, but the netANALYZER hardware is not installed in the PC or not connected.</td>
<td>The netANALYZER hardware installed in the PC and connect.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The netSCOPE device is disabled in the device manager.</td>
<td>Enable the netSCOPE device in Device Manager.</td>
</tr>
<tr>
<td>0x80220003</td>
<td>NETANA_DEVICE_NOT_FOUND</td>
<td>Device with the given name does not exist</td>
<td>The netSCOPE device was removed from the PC during operation of the netSCOPE software.</td>
<td>Update the netSCOPE Software device list.</td>
</tr>
<tr>
<td>0x80220004</td>
<td>NETANA_DEVICE_STILL_OPEN</td>
<td>Device is still in use by another application</td>
<td>The netSCOPE device was already opened in another application.</td>
<td>Close the netSCOPE device in the other application or select another device.</td>
</tr>
</tbody>
</table>

**Table 13: Toolkit Errors Description**
### 4.6 Capturing Errors

<table>
<thead>
<tr>
<th>Value</th>
<th>Error Code (Definition)</th>
<th>Description</th>
<th>Possible Causes</th>
<th>Troubleshooting</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xC0660004</td>
<td>NETANA_CAPTURE_ERROR_NO_DMACHANNEL</td>
<td>No free DMA channel available. Probably host is too slow</td>
<td>The data load of the capturing is too high.</td>
<td>Check whether the hard disk of the PC is fast enough to save the captured data. The theoretical maximum load is 50 MB/s. Reduce the load of the data to be captured.</td>
</tr>
<tr>
<td>0xC0660005</td>
<td>NETANA_CAPTURE_ERROR_URX_OVERFLOW</td>
<td>XC buffer overflow (URX overflow)</td>
<td>Occurs because a non IEEE802.3 conform traffic is captured (e.g. too short frames, too small IFG).</td>
<td>Record only IEEE802.3-compliant message traffic.</td>
</tr>
<tr>
<td>0xC066000B</td>
<td>NETANA_CAPTURE_ERROR_NO_HOSDBUFFER</td>
<td>No free DMA buffer available.</td>
<td>Host is too slow to handle data efficiently.</td>
<td>Check whether the hard disk of the PC is fast enough to save the captured data. The theoretical maximum load is 50 MB/s. Reduce the load of the data to be captured.</td>
</tr>
<tr>
<td>0xC066000C</td>
<td>NETANA_CAPTURE_ERROR_NO_INTRAMBUFFER</td>
<td>Internal capture buffer overflow</td>
<td>No free INTRAM Firmware is out of memory resources and is unable to buffer more data. This may also be caused by a slow file system or a slow application</td>
<td>Check whether the hard disk of the PC is fast enough to save the captured data. The theoretical maximum load is 50 MB/s. Reduce the load of the data to be captured.</td>
</tr>
<tr>
<td>0xC066000D</td>
<td>NETANA_CAPTURE_ERROR_FIFO_FULL</td>
<td>Firmware is out of FIFO resources and is unable to buffer more data. This may also be caused by a slow file system or a slow application</td>
<td>This error is triggered when the ringbuffer mode is not activated and the end of capture file is reached.</td>
<td>Optimize your application or use a faster PC.</td>
</tr>
<tr>
<td>0xC0770000</td>
<td>NETANA_CAPTURE_ERROR_DRIVER_FILE_FULL</td>
<td>End of capture file reached. Driver has stopped capturing.</td>
<td>The error is triggered when the ringbuffer mode is not activated and the end of capture file is reached.</td>
<td>No error</td>
</tr>
</tbody>
</table>

**Table 14: Capturing Errors Description**
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5.4 Glossary

ENI

**EtherCAT Network Information**

The EtherCAT Network Information (ENI) Specification describes the structure of ENI files using XML schemas.

**EtherCAT**

A communication system for industrial Ethernet designed and developed by Beckhoff Automation GmbH.

**LabVIEW**

**Laboratory Virtual Instrumentation Engineering Workbench**
LabVIEW is a graphical programming system from National Instruments. It is the leading graphical programming language for measurement and automation applications.

**netSCOPE**

Hilscher's netSCOPE is a tool to capture network traffic from Real-Time Ethernet systems and to display data content for analysis purposes.

**VI**

Virtual Instrument

LabVIEW programs/subroutines are called virtual instruments (VIs).
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