



Operating Instruction Manual
Generic Slave DTM for EtherCAT Slave Devices
Configuration of EtherCAT Slave Devices

Hilscher Gesellschaft für Systemautomation mbH

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1 Introduction

1.1 About this Manual

This manual provides information on how to set up EtherCAT Slave devices described with XML DDF files. These devices can be configured with the EtherCAT generic Slave DTM within an FDT Framework.

1.1.1 Descriptions of the Dialog Panes

The table below gives an overview for the individual dialog panes descriptions:

Section	Subsection	Manual Page
Configuration	Overview Configuration	17
	General	19
	Behavior	20
	State Machine Timeout	21
	Device Check-up	22
	Process Data	23
	Watchdog	24
	Distributed Clock	25
	Process Data	30
	Sync Manager	31
	PDO Assignment (Index 0x1C10- 0x1C1F)	33
	PDO Content (Index 0x1600-0x17FF, 0x1A00-0x1BFF)	35
	Mailbox	36
	CoE	36
Description	Overview Description	37
	XML DDF Viewer	38

Table 1: Overview Dialog Pages

1.1.2 Online Help

The generic EtherCAT Slave DTM contains an integrated online help facility.

- To open the online help, click on **Help** or press **F1**.

1.1.3 List of Revisions

Index	Date	Version	Component	Chapter	Revisions
4	12-09-27	0.912.x.x	ECATGenericSlaveDTM.dll ECATGenericSlaveGUI.ocx	all, 1.3.1, 3.4 3.6 3.7.1	Revised, Section <i>Requirements</i> updated, Check boxes 'Serial number' and 'include WC state Bit(s)' have been removed in section „ <i>Behavior</i> “ Update of <i>Figure 18:</i> <i>Configuration > Process data</i> Update of <i>Figure 22:</i> <i>Configuration > Mailbox > CoE</i> <i>Mailbox Settings</i>
5	13-01-23	0.922.x.x	ECATGenericSlaveDTM.dll ECATGenericSlaveGUI.ocx	1.3.1 3.4.4 3.4.4 1.4.2, 3.1	Section <i>Requirements</i> , Windows 8 added. Removed option „Include WC state Bit(s)“ Removed option „Serial number“ Adapted menu tree for new entry „Distributed Clocks“

1.1.4 Conventions in this Manual

Notes, operation instructions and results of operation steps are marked as follows:

Notes



Important: <important note>



Note: <note>



<note, where to find further information>

Operation Instructions

1. <instruction>
2. <instruction>

or

➤ <instruction>

Results

⇒ <result>

1.2 Legal Notes

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1.3 About EtherCAT Generic Slave DTM

You can use the EtherCAT generic Slave DTM to configure the EtherCAT Slave devices described with XML DDF files within a FDT Framework.

The information necessary for the configuration of the EtherCAT Slave devices is stored within the EtherCAT Master device when using the EtherCAT generic Slave DTM and thus the Master device is configured.

1.3.1 Requirements

System Requirements

- PC with 1 GHz processor or higher
- Windows® XP SP3, Windows® Vista (32 bit) SP2, Windows® 7 (32 bit) SP1, Windows® 7 (64 bit) SP1, Windows® 8 (32 bit) or Windows® 8 (64 bit)
- Administrator privilege required for installation
- Internet Explorer 5.5 or higher
- RAM: min. 512 MByte, recommended 1024 MByte
- Graphic resolution: min. 1024 x 768 pixel
- Keyboard and Mouse



Note: If the project file is saved and opened again or if it is used on another PC, the system requirements must match. Particularly the DTM must be installed on the used PC.

Restriction

Touch screen is not supported.

Requirements EtherCAT Generic Slave DTM

Requirements for working with the EtherCAT generic Slave DTM are:

- Installed FDT/DTM V 1.2 compliant frame application
- Installed EtherCAT Master DTM
- DDF file of the devices to be configured
- The user needs to reload the Device Catalog

Loading XML DDF files

To add devices to the **netDevice** device catalog, you must import the XML DDF file of the used device via **netDevice** menu **Network > Import Device Descriptions** into the DDF folder of the DTM. Then the Device Cataloge must be reloaded. The folder DDF inclusively Windows® XP is located in the application data directory (All Users) of the configuration software (or from with Windows® 7 on in the *C:\ProgramData\ SYCONnet* directory).



For further information refer to section *Configuration Steps* on page 16 , under step 1 and 2.

1.4 Dialog Structure of the EtherCAT Generic Slave DTM

The graphical user interface of the DTM is composed of different areas and elements listed hereafter:

1. A header area containing the **General Device Information**,
2. The **Navigation Area** (area on the left side),
3. The **Dialog Pane** (main area on the right side),
4. **OK, Cancel, Apply, Help**,
5. The **Status Line** containing information e. g. the online-state of the DTM.

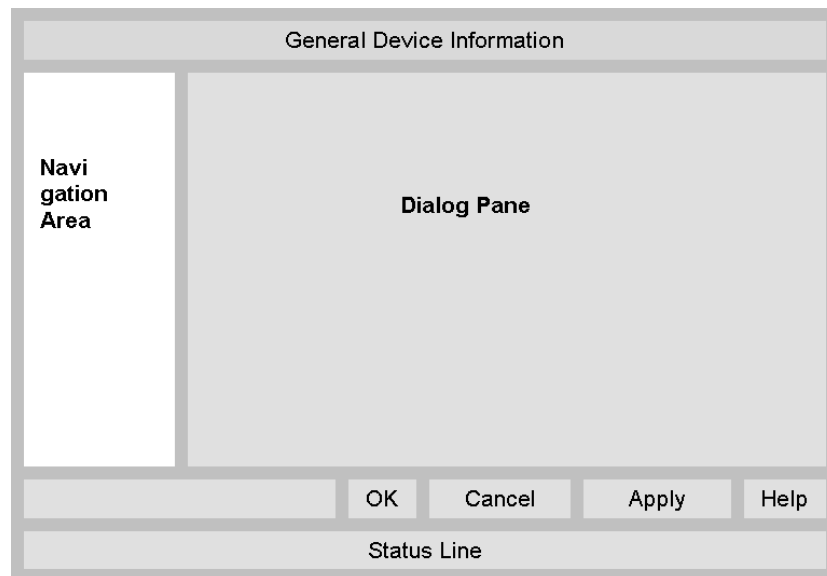


Figure 1: Dialog Structure of the Generic EtherCAT Slave DTM

1.4.1 General Device Information

Parameter	Meaning
IO Device	Name of the device
Vendor	Vendor name of the device
Device ID	Identification number of the device
Vendor ID	Identification number of the vendor

Table 2: General Device Information

1.4.2 Navigation Area

The **Navigation Area** contains folders and subfolders to open the dialog panes of the DTM.

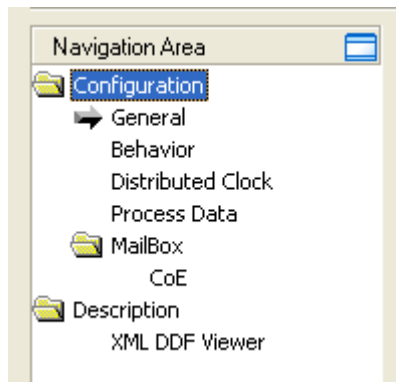




Figure 2: Navigation Area

- Select the required folder and subfolder.
- The corresponding Dialog pane is displayed.

Hide / display Navigation

	Hiding the navigation area (above right side).
 Show navigation area	Opening the navigation area (below left side).

1.4.3 Dialog Pages

At the dialog pane the **Configuration** or **Description** panes are opened via the corresponding folder in the navigation area.

Configuration	
General	At the General pane EtherCAT Slave information is displayed. For further information, refer to section <i>General</i> on page 19.
Behavior	At pane Behavior the parameters of the Device checkup, the Process Data and the Watchdog are described. For further information, refer to section <i>Behavior</i> on page 20.
Distributed Clock	At the pane Distributed Clock , the DC Sync mechanism and Sync0 and Sync1 can be activated and the parameters Sync 0 Cycle Time, Sync 0 Shift Time, Sync 1 Cycle Time and Sync1 Shift Time can be determined and set. For further information, refer to section <i>Distributed Clock</i> on page 25.
Process data	At pane Process Data the parameters of the Sync Manager are displayed, the PDO Assignment and the PDO content. For further information, refer to section <i>Process Data</i> on page 30.
Mailbox	At pane Mailbox you can get information on mailbox-based data transfer and the CoE (CANopen over Ethernet) functionality. For further information, refer to section <i>Mailbox</i> on page 33.
Description	
XML DDF Viewer	By use of the XML DDF-Viewer a DDF file can be viewed and searched through. For further information, refer to section <i>XML DDF Viewer</i> on page 38.

Table 3: Overview Dialog Panes

1.4.4 OK, Cancel, Apply and Help

OK, Cancel, Apply and Help you can use as described hereafter.

	Meaning
OK	To confirm your latest settings, click OK . All changed values will be applied on the frame application database. <i>The dialog then closes.</i>
Cancel	To cancel your latest changes, click Cancel . Answer to the safety query Configuration data has been changed. Do you want to save the data? by Yes , No or Cancel . Yes: The changes are saved or the changed values are applied on the frame application database. <i>The dialog then closes.</i> No: The changes are <u>not</u> saved or the changed values are not applied on the frame application database. <i>The dialog then closes.</i> Cancel: <i>Back to the DTM.</i>
Apply	To confirm your latest settings, click Apply . All changed values will be applied on the frame application database. <i>The dialog remains opened.</i>
Help	To open the DTM online help, click Help .

Table 4: OK, Cancel, Apply and Help

1.4.5 Table Lines

In the DTM dialog pane table lines can be selected, inserted or deleted.

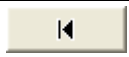





	Meaning
	To select the first line of a table use First Line .
	To select the previous line of a table use Previous Line .
	To select the next line of a table use Next Line .
	To select the last line of a table use Last Line .
	Create a new Line inserts new lines into the table.
	Delete selected Line deletes the selected line from the table.

Table 5: Selecting, inserting, deleting Table Line

1.4.6 Status Bar

The **Status Bar** displays information about the current state of the DTM. The current activity, e.g. the DTM connection state, is signaled graphically via icons in the status bar.

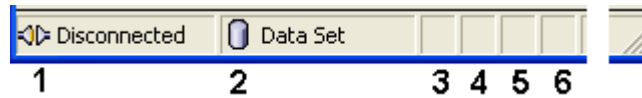


Figure 3: Status Bar – Status Fields 1 to 6






Status Field	Icon / Meaning
1	DTM Connection States
	 Connected: Icon closed = Device is online
	 Disconnected: Icon opened = Device is offline
2	Data Source States
	 Data set: The displayed data are read out from the instance data set (database).
	 Device: The displayed data are read out from the device.
3	States of the instance Date Set
	 Valid Modified: Parameter is changed (not equal to data source).

Table 6: Status Bar Icons [1]

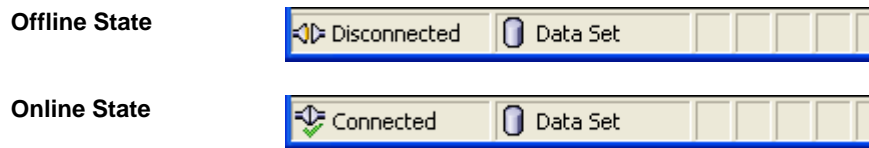


Figure 4: Status Bar Display Example

2 Getting started

2.1 Configuration Steps

The following table describes the steps to configure a EtherCAT Slave device with the EtherCAT generic Slave DTM as it is typical for many cases. At this time it is presupposed that the EtherCAT Master DTM installation was already done.

#	Step	Short Description	For detailed information see section	Page
1	Add EtherCAT Slave in the Device Catalog	Add the Slave in the Device Catalog by importing the device description file to the Device Catalog. Depending of the FDT Container. For netDevice: - Network > Import Device Descriptions.	<i>(See Operating Instruction Manual netDevice and netProject)</i>	-
2	Load device catalog	Depending of the FDT Container: For netDevice: - select Network > Device Catalog, - select button Reload Catalog.	<i>(See Operating Instruction Manual netDevice and netProject)</i>	-
3	Create new project / Open existing project	Depending of the frame application. For the configuration software: - select File > New or File > Open.	<i>(See Operating Instruction Manual of the Frame Application)</i>	-
4	Insert Master or Slave into configuration	Depending of the FDT Container: For netDevice: - in the Device Catalog click to the Master, - and insert the device via drag and drop to the line in the network view, - in the Device Catalog click to the Slave, - and insert the device via drag and drop to the Master bus line in the network view.	-	-
5	Configure Slave	Configure the Slave. - Double click to the device icon of the Slave. - The generic Slave DTM configuration dialog is displayed. In the generic Slave DTM configuration dialog: - configure the EtherCAT device parameters. - close the generic Slave DTM configuration dialog via the button OK.	<i>Configuring Device Parameters</i>	18
6	Configuration Steps Master device	Configure the Master device via EtherCAT-Master DTM.	<i>(See Operating Instruction Manual DTM for EtherCAT-Master devices)</i>	-
7	Save project	Depending of the frame application. For the configuration software: - select File > Save.	<i>(See Operating Instruction Manual of the Frame Application)</i>	-

Table 7: Getting started - Configuration Steps

3 Configuration

3.1 Overview Configuration

Dialog Panes “Configuration”

The table below gives an overview about the available **Configuration** dialog panes descriptions:

Section	Manual Page
Overview Configuration	17
General	19
Behavior	20
State Machine Timeout	21
Device Check-up	22
Process Data	23
Watchdog	24
Distributed Clock	25
Process Data	30
Sync Manager	31
PDO Assignment (Index 0x1C10- 0x1C1F)	33
PDO Content (Index 0x1600-0x17FF, 0x1A00-0x1BFF)	35
Mailbox	36
CoE	36
Overview Description	37
XML DDF Viewer	38

Table 8: Descriptions of the Dialog Pages Configuration

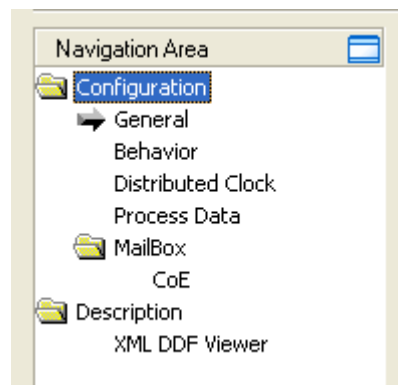


Figure 5: Navigation Area - Configuration



For information to further steps as **Download Configuration** or **Diagnosis**, refer to the Operating Instruction Manual *DTM for EtherCAT Master devices*.

3.2 Configuring Device Parameters

The following steps are needed to configure the device parameters using the EtherCAT generic Slave DTM:

- Configure the behavior of the EtherCAT-Slave as described in section “*Behavior*” at page 20.
- On the **Behavior** page set the parameters for
 - the Device checkup,
 - the **Process data**
 - and the **Watchdog**.
- Configure the process data of the EtherCAT-Slave as described in section *Distributed Clock* at page 25.
- On the **Process Data** page set the parameters for
 - the **Sync Manager**,
 - the **PDO Assignment (0x1C10-0x1C2F)**
 - and the **PDO Content (0x1600-0x17FF)**.

3.3 General

The **General** dialog page shows the **Description** of the EtherCAT Slave.



Note: The **Station Address** is set by the EtherCAT Master, therefore the corresponding data field is not editable.

General

Description:

Device type:

Device name:

Product revision:

Physics:

Station Address:

Note: Station Addresses are logical ones and are set in Master DTM for all slaves.

Figure 6: Configuration > General

Parameter	Meaning
Description	Symbolic Name of the EtherCAT Slave station.
Device type	Device type as defined in the DDF
Device name	Device name as defined in the DDF
Product revision	Product revision as defined in the DDF or E ² PROM
Physics	EtherCAT Port configuration: available ports and their types.
Station Address	Station Address denominates a logical address. The station address of a slave is set in the master DTM.

Table 9: General Page Parameters

Physics in the context of EtherCAT Port configuration is described by two characters indicating the physical interface of the connection. The coding is as follows:

Physics	Port type
K	E-Bus
Y	100Base-TX
F	100Base-FX

Table 10: Coding of Parameter "Physics"

3.4 Behavior

At the page **Behavior**, the parameters of

- the state machine timeout values
- the device checkup,
- the process data
- and the watchdog timer.

are set and displayed.

Behavior

State Machine Timeout (ms)

I2P:	3000
P2S, S2O:	10000
Back to P, I:	5000
O2S:	200

Device checkup

VendorID

Product code

Revision

Process data

Use LRD/LWR instead of LRW

Watchdog

<input type="checkbox"/> Set multiplier (Reg. 400 h):	2498	
<input type="checkbox"/> Set PDI watchdog (Reg. 410 h):	1000	ms
<input type="checkbox"/> Set SM watchdog (Reg. 420 h):	1000	ms

Figure 7: Configuration > Behavior

3.4.1 State Machine Timeout

For various transitions between states of the EtherCAT slave state machine the associated timeout values can be configured separately in the state machine timeout section of the 'Behavior' dialog:

- **I2P**
This value applies to the transition from *Init* state to *Pre-Operational* state
- **P2S, S2O**
This value applies to the transition from *Pre-Operational* state to *Safe-Operational* state and from *Safe-Operational* state to *Operational* state.
- **Back to P, I**
This value applies to the transition from any higher state back to *Pre-Operational* state or *Init* state.
- **O2S**
This value applies to the transition from *Operational* state to *Safe-Operational* state.



Note: These timeout values are specified in units of milliseconds.

State Machine Timeout (ms)	
I2P:	3000
P2S, S2O:	10000
Back to P, I:	5000
O2S:	200

Figure 8: Configuration > Behavior > State Machine Timeout - Configuration

3.4.2 Device Check-up

The *device check-up* part of the **Behavior** dialog looks like:

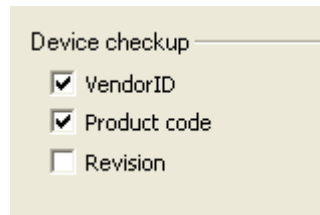


Figure 9: Configuration > Behavior > Device Check

The following table shows which items identifying the EtherCAT device can optionally be verified during device check-up if marked in the dialog accordingly.

Parameter	Meaning
VendorID	Device's vendor ID (DDF or stored device-internally)
Product code	Device's product code (DDF or stored device-internally)
Revision	Device's revision (DDF or stored device-internally)

Table 11: Parameters Behavior > Device checkup

The values within the DDF file are verified against the corresponding information stored in the device (for example, within an E²PROM circuit), if the according check box is marked.

3.4.3 Process Data

EtherCAT supplies different command sets for reading and writing:

- a combined read/write command (LRW)
- separate read and write commands (LRD/LWR)

This option allows to choose between these alternatives:

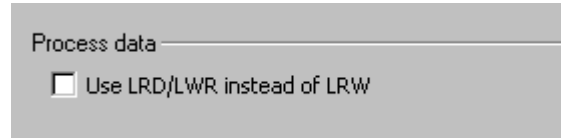


Figure 10: Configuration > Behavior > Process data

Parameter	Meaning
Use LRD/LWR instead of LRW	Logical read and write operation: If marked, separate EtherCAT read (LRD) and write (LWR) commands will be used. Otherwise, a combined EtherCAT read and write (LRW) command will be used.

Table 12: Parameters Behavior > Process data

For more information on EtherCAT read and write commands see the *EtherCAT Communication Specification*, version 1.0, section 6.2 “EtherCAT Services”, page 43.

3.4.4 Watchdog

Both the entire PDI (Process Data Interface) and all sync managers (separately) are monitored by watchdog timers.

The following rules apply for resetting the watchdog timers:

- Each access from the application controller to the EtherCAT Slave controller resets the watchdog timer of the Process Data Interface.
- Each write access to the associated memory area of a sync manager resets the sync manager’s watchdog timer.

The watchdog timeout values can be calculated using the formula given below from an individually configurable value and a common multiplier.

The “Watchdog” part of the “*Behavior*” dialog allows specifying the multiplier and the individual values for PDI watchdog and sync manager watchdogs.

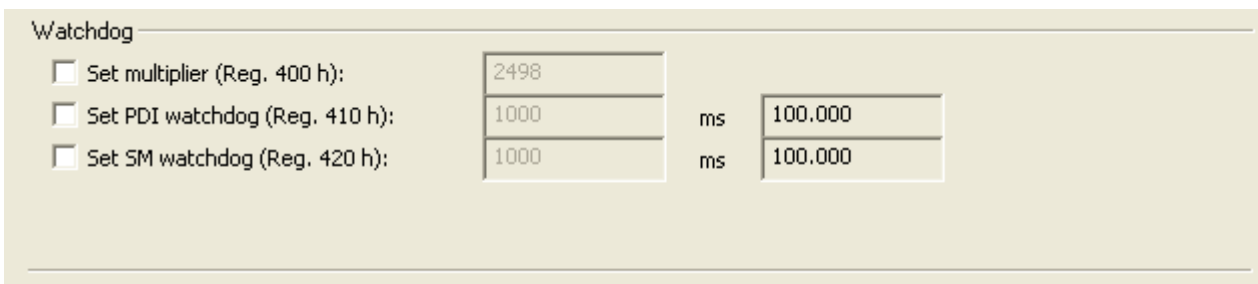


Figure 11: Configuration > Behavior > Watchdog

Parameter	Meaning
Set multiplier	Watchdog multiplier, content of the register 0x400
Set PDI watchdog	PDI watchdog, see note below
Set SM watchdog	SM watchdog, see note below

Table 13: Parameters Behavior > Watchdog



Note: The **PDI & SM** watchdog timeout values are calculated as follows.

PDI watchdog timeout =

$$([\text{value of register } 0x400] + 2) * 40 * [\text{value of register } 0x 410]$$

SM watchdog timeout =

$$([\text{value of register } 0x 400] + 2) * 40 * [\text{value of register } 0x 420]$$

3.5 Distributed Clock

At the page **Distributed Clock**, the DC Sync mechanism and Sync0 and Sync1 can be activated and the parameters

- Sync 0 Cycle Time,
- Sync 0 Shift Time,
- Sync 1 Cycle Time
- and Sync1 Shift Time

can be determined and set:

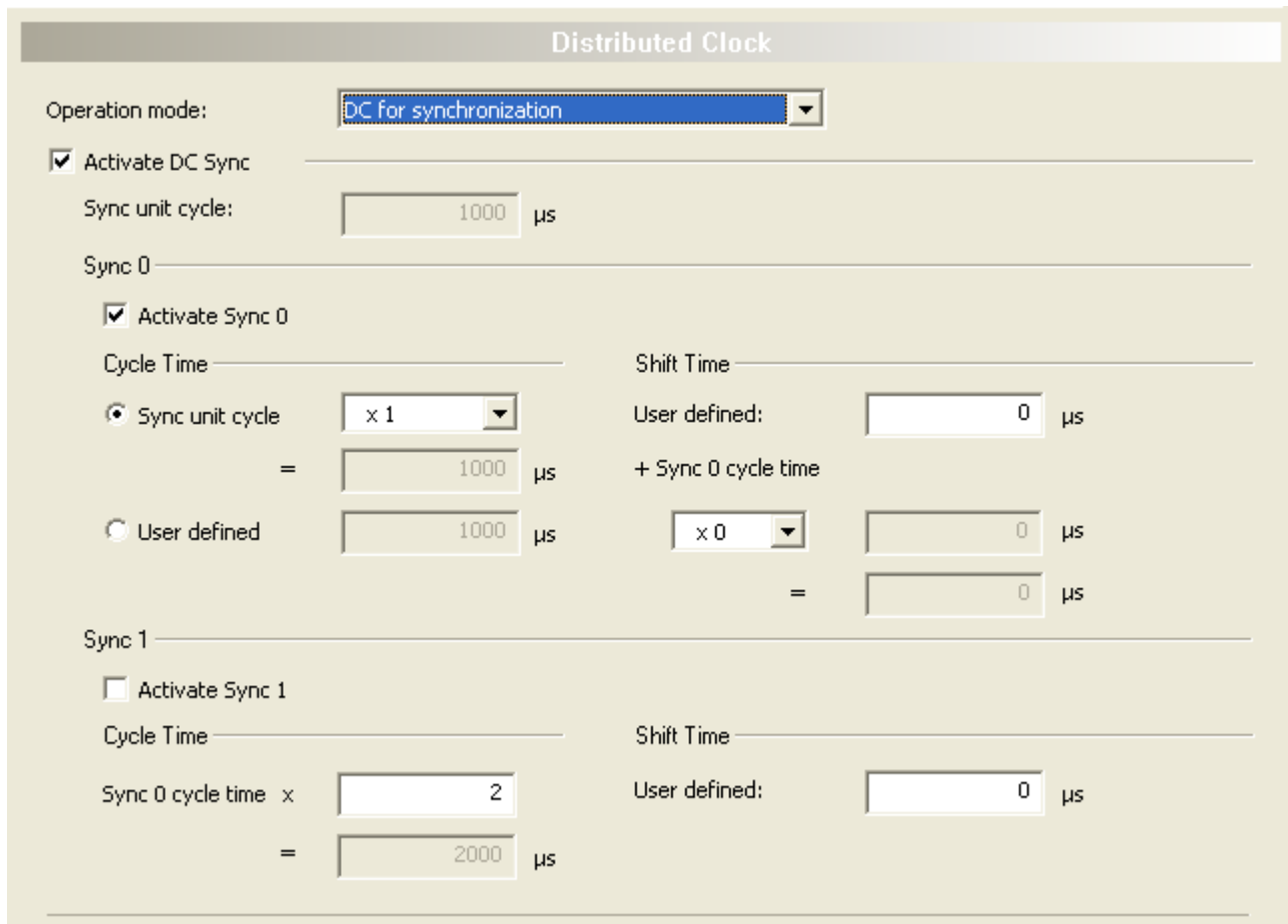


Figure 12: Configuration > Distributed Clock

Operation Mode

There are three operation modes available for Distributed Clocks. These are:

- *DC unused*
- *DC for synchronization*
- *User-defined Operation Mode*

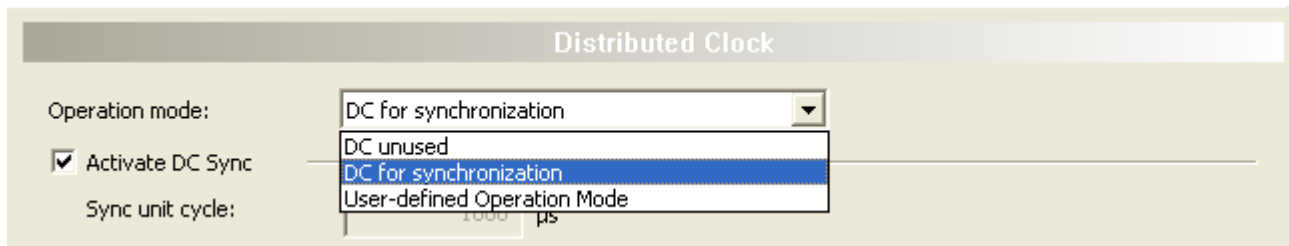


Figure 13: Operation Mode

Activate DC Sync

In order to set up Sync0 and Sync1 the check box *Activate DC Sync* has to be set. Data can only be entered into this screen if the check box *Activate DC Sync* is checked. Otherwise all subsequent input fields, selection lists and check boxes are grayed out and deactivated.

Sync Unit Cycle

The value displayed here is taken from the EtherCAT Master settings (Free run cycle time i.e. the cycle time of the EtherCAT-Master running free) as it is adjustable not at the EtherCAT Generic Slave but at the EtherCAT Master. Therefore the field is grayed out and disabled here

3.5.1 Sync 0

Checkbox “Activate Sync 0”

Sync 0 can be activated and deactivated by checking and unchecking the check box “**Activate Sync 0**”.

3.5.1.1 Sync 0 Cycle Time



Note: Whether this value can be adjusted or not depends on the Device Description File of the appropriate device.

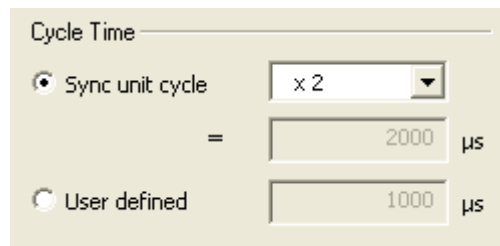
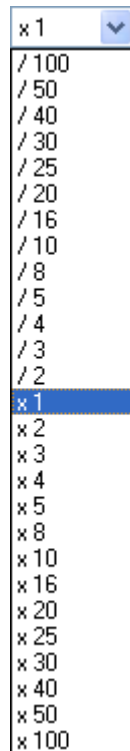


Figure 14: Sync 0 Cycle Time

The Sync 0 Cycle Time can either be derived from the Sync Unit Cycle Time adjusted at the EtherCAT Master (see above) by multiplying it with a factor or it can be entered directly.

For calculating the Sync 0 Cycle Time from the Sync Unit Cycle Time, check the check box „*Sync Unit Cycle*“. The Sync Unit Cycle Time is multiplied with (or divided by) an adjustable factor.

The following factors are available within the selector list:



For specifying the Sync 0 Cycle Time directly, check the check box „User defined“. The value is specified in units of microseconds. The default value is 1000 microseconds. The allowed values range from 0 to 4,294,967.295 microseconds. If the specified value violates one of these limits, an error message is issued.

3.5.1.2 Sync 0 Shift Time

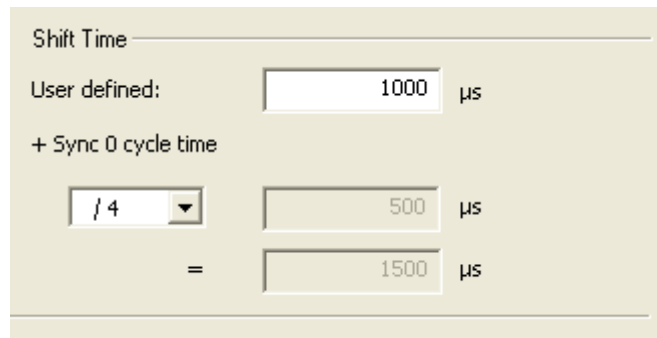
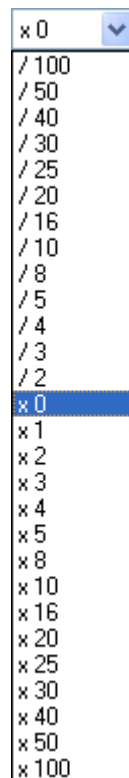


Figure 15: Sync 0 Shift Time

The Sync 0 Shift Time is calculated in the following way:

The Sync 0 Cycle Time is multiplied with (or divided by) an adjustable factor, the Sync 0 Shift Time Modifier.

The following values are available within the selector list:



Note: In contrast to the Sync 0 Cycle Time described above, here also the factor 0 may be chosen!

The default value for this factor is

- 0: if the chosen operation mode (see above) is *DC for synchronization*
- 1: otherwise.

Then the value specified in the input field *User defined* is added to the product. The allowed range of values extends from -2147483.648 to +2147483.647. If a value outside of these limits is specified, an error message will be issued.

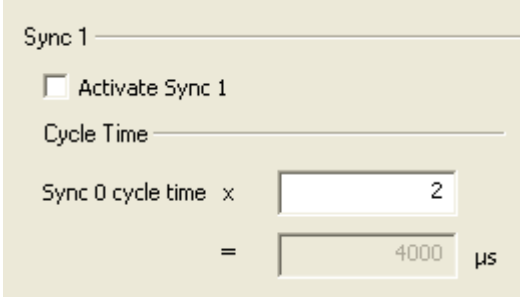
The sum is displayed in the lower field having been grayed out. It is now used as the Sync 0 Shift Time.

3.5.2 Sync 1

3.5.2.1 Checkbox “Activate Sync 1”

Sync 1 can be activated and deactivated by checking and unchecking the check box “**Activate Sync 1**”.

3.5.2.2 Sync 1 Cycle Time



The screenshot shows a configuration window for Sync 1. At the top, it says "Sync 1". Below that is a checkbox labeled "Activate Sync 1" which is currently unchecked. Underneath is the label "Cycle Time". Below that is a calculation: "Sync 0 cycle time x" followed by an input field containing the number "2". Below this is an equals sign followed by another input field containing "4000" and the unit "µs".

Figure 16: Sync 1 Cycle Time

The Sync 1 Cycle Time is calculated as the product of the Sync 0 Cycle Time (see subsection “*Sync 0*” above) with a positive integer factor that is specified in the input field right of *Sync 0 cycle time x*.

The range of allowed factors extends from 1 to 1024. If a value violating these limits is entered, an error message will be issued.

The product is then displayed in the grayed out field just below of the input field.

3.5.2.3 Sync 1 Shift Time



The screenshot shows a configuration window for Sync 1 Shift Time. At the top, it says "Shift Time". Below that is the label "User defined:" followed by an input field containing the number "0" and the unit "µs".

Figure 17: Sync 1 Shift Time

3.6 Process Data

In EtherCAT, the process data objects (PDO) are assigned to sync managers. A sync manager is used for synchronization of data communication on a certain communication channel. This channel is configured either for input or for output and either for cyclic or for acyclic communication. (This is defined within the device description file.) Up to 16 sync manager can be configured. These are numbered from 0 up to 15. The process data dialog only displays the sync manager which is for cyclic communication. Possible sync managers for acyclic communication is displayed in the **CoE MailBox** dialog.

The illustration below shows the process data dialog of the EtherCAT Generic Slave DTM:

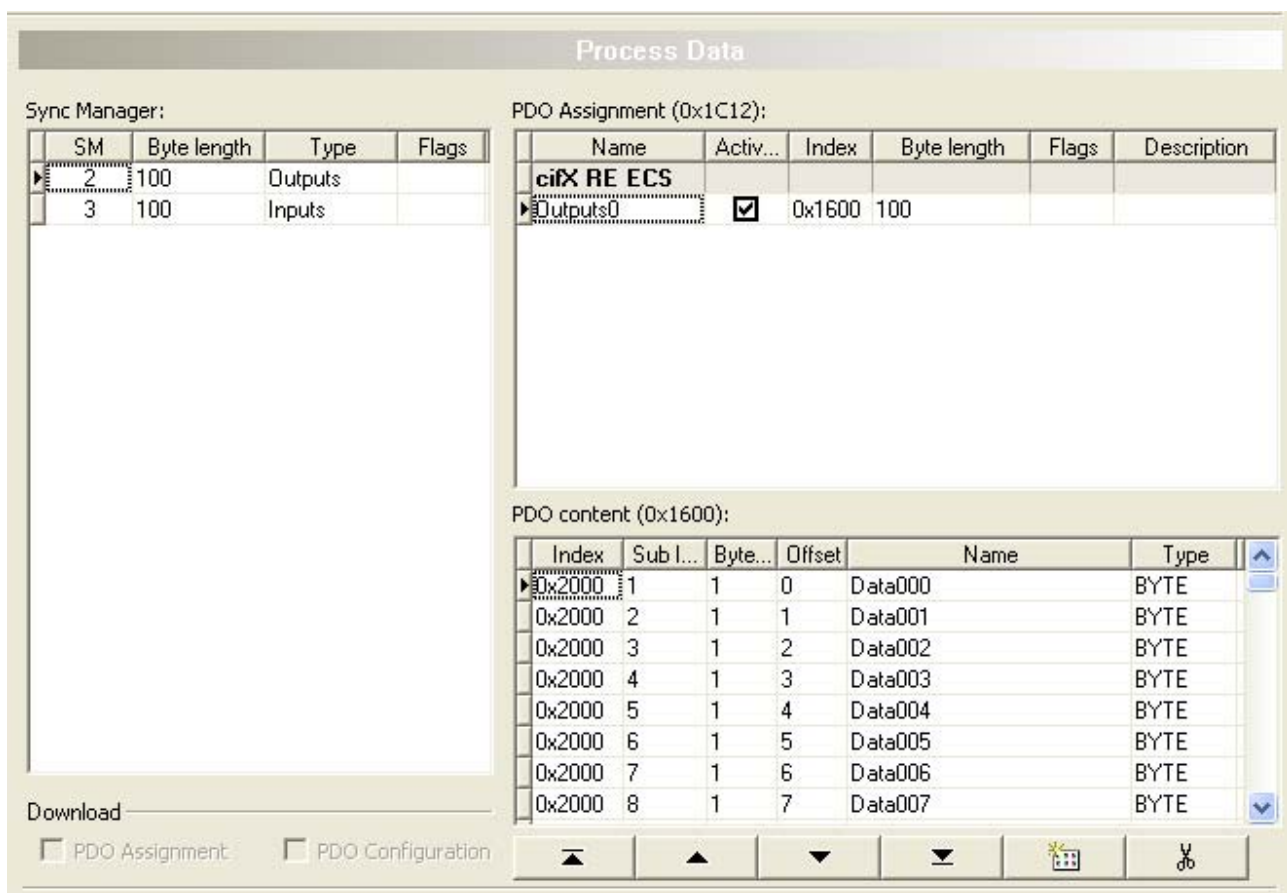


Figure 18: Configuration > Process data

The process data dialog consists of three parts:

- Sync Manager area
- PDO Assignment area
- PDO Content area

3.6.1 Sync Manager

Within the process data dialog only those PDOs can be shown simultaneously, which are assigned to the same sync manager.

The left part of the process data dialog represents the *Sync Manager* area which is used for choosing the sync manager to be used. It provides the **Sync Manager** table for choosing the sync manager whose PDOs are to be displayed, and additionally two checkboxes for PDO assignment and PDO configuration which however are relevant in case of variable configuration only.

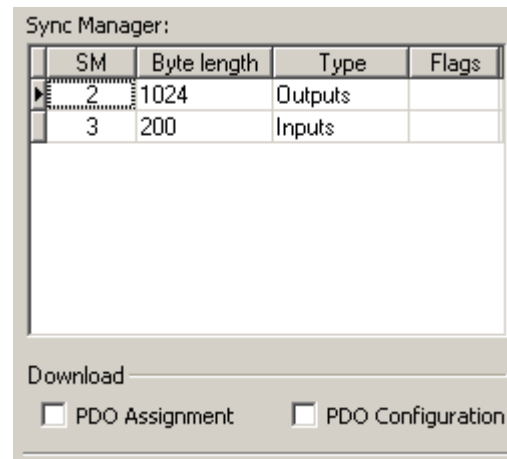


Figure 19: Configuration > Process data > Sync Manager

The table **Sync Manager** displays the configuration of the sync managers for the device, as defined in its device description file (DDF). For each of the 4 sync managers available at maximum in the table, the following information is displayed:

Parameter	Meaning
SM	Sync Manager channel number (0-15)
Byte length	Sync Manager length in bytes
Type	Sync Manager type (Inputs/ Outputs)
Flags	Sync Manager flags (Flag F = fixed contents)

Table 14: Parameters Process data > Sync Manager

In case this device supports acyclic communication based on mailboxes the Sync Manager 0 is used for the mailbox output (master to slave) and the Sync Manager 1 is used for the mailbox input (slave to master).

If the device does not support acyclic communication based on mailboxes, Sync Manager 0 - 15 can be used for the Process data outputs and inputs (also see Figure *Configuration > Process data > Sync Manager*).

The size of the Sync Managers is defined by the assigned PDO objects. In this case the PDO object is assigned to the Sync Manager 3 and because the content of this object has the size 8 the Sync Manager is configured to 8 bytes.

The read-only checkboxes below show the download flags which are defined in device description file. They have the following meaning:

Checkbox	Meaning
PDO Assignment	<p>This flag indicates whether to download PDO assignment of Sync Manager.</p> <p>If this flag is checked, this means that PDO assignment of the slave is writable and special CoE Init-Commands should be generated by the EtherCAT Master DTM in the Configuration Information File.</p> <p>These CoE Init-commands include the indices of transmit/receive PDOs. Therefore the slave knows how such PDOs are related to the Sync Manager.</p>
PDO Configuration	<p>This flag indicates whether to download PDO mapping.</p> <p>If this flag is set as checked, this means that PDO mapping of the slave is writable and special CoE Init-Commands should be generated by the EtherCAT Master DTM in the Configuration Information File.</p> <p>These CoE Init-Commands include the indices of mapped process data objects. Therefore slave knows how mapped PDOs are related to transmit /receive PDOs.</p>

Table 15: Meaning of Checkboxes

3.6.2 PDO Assignment (Index 0x1C10- 0x1C1F)

The upper right part of the process data dialog represents the *PDO Assignment* area for the sync manager chosen within the left part of the window. It contains the transmit/receive PDOs.

Thus the contents of this table depends on the choice of the sync manager in the left part of the window. If a sync manager with type “Outputs” is selected, all defined receive PDOs (Index 0x1600 -0x17FF) in the device description file will be shown in this table.

Similarly, if a sync manager with type “Inputs” is selected, all defined transmit PDOs (Index 0x1A00 -0x1BFF) will be shown in this table.

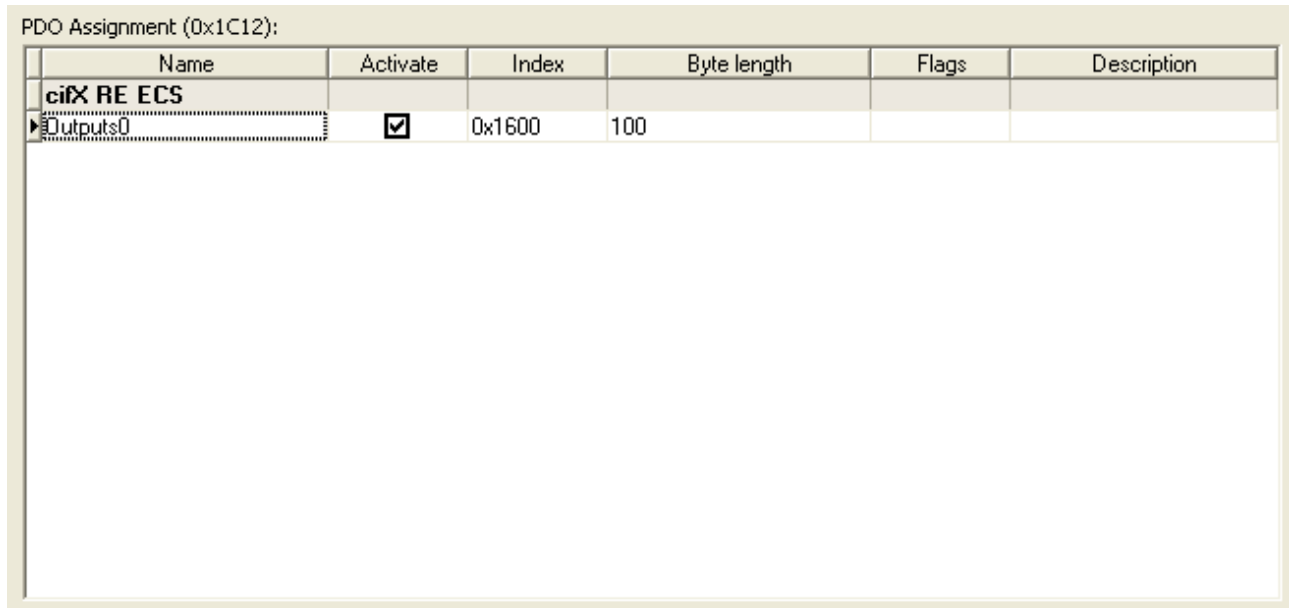


Figure 20: Configuration > Process data > PDO Assignment

For the transmit/receive PDOs assigned to the chosen sync manager, the following values are displayed:

Parameter	Meaning
Name	Name of the PDO
Activate	Activation check box for assigned PDO of the selected Sync Manager
Index	Object index of the PDO
Byte length	Length of the PDO in bytes
Flags	Flags assigned to the PDO
Description	Description of the PDO

Table 16: Parameters Process data > PDO Assignment

The PDO assignment is stored in a sync manager channel object within the object dictionary of the EtherCAT slave. The index of such an object is displayed in the headline of the PDO assignment area, and it has a relationship with the sync manager channel number(n) :

$$\text{Index} = 0x1C10 + n \quad (n = 0 \dots 15)$$

In the current example the information was taken from the object with the index 0x1C12 indicating sync manager 2 had been chosen for display.

For slave devices with selectable PDO assignment, PDO/PDOs can be selected from the given list of multiple fixed PDOs according to the rules defined by the device description file.

3.6.3 PDO Content (Index 0x1600-0x17FF, 0x1A00-0x1BFF)

The lower right part of the process data dialog represents the *PDO Content* area. It contains the mapped process data objects of the transmit/receive PDO, which has been selected in the upper right part of the window.

Index	Sub Index	Byte length	Offset	Name	Type
0x2000	1	1	0	Data000	BYTE
0x2000	2	1	1	Data001	BYTE
0x2000	3	1	2	Data002	BYTE
0x2000	4	1	3	Data003	BYTE
0x2000	5	1	4	Data004	BYTE
0x2000	6	1	5	Data005	BYTE
0x2000	7	1	6	Data006	BYTE
0x2000	8	1	7	Data007	BYTE
0x2000	9	1	8	Data008	BYTE
0x2000	10	1	9	Data009	BYTE
0x2000	11	1	10	Data010	BYTE
0x2000	12	1	11	Data011	BYTE
0x2000	13	1	12	Data012	BYTE
0x2000	14	1	13	Data013	BYTE

Figure 21: Configuration > Process Data > PDO Content

For the mapped process data objects, the following values are displayed:

Parameter	Meaning
Index	Object index Subindex of the PDO
Sub index	Sub index for the PDO
Byte length	Size of the PDO entry in Byte
Offset	Offset of the PDO entry (relative to 0x1600 for output and to 0x1A00 for input PDOs)
Name	Name of the PDO entry
Type	Data type of the PDO entry

Table 17: Parameters Process Data > PDO Content

The PDO content is stored in a transmit/receive object within the object dictionary of the EtherCAT slave. You can find the correct index of the selected transmit/receive PDO in the headline of the PDO assignment area.

In the current example the information was taken from the object with index 0x1604.

For an explanation of the navigation buttons see section “Table Line” of this document.

3.7 Mailbox

3.7.1 CoE

For slave devices supporting the CoE MailBox, the following dialog page is additionally displayed:

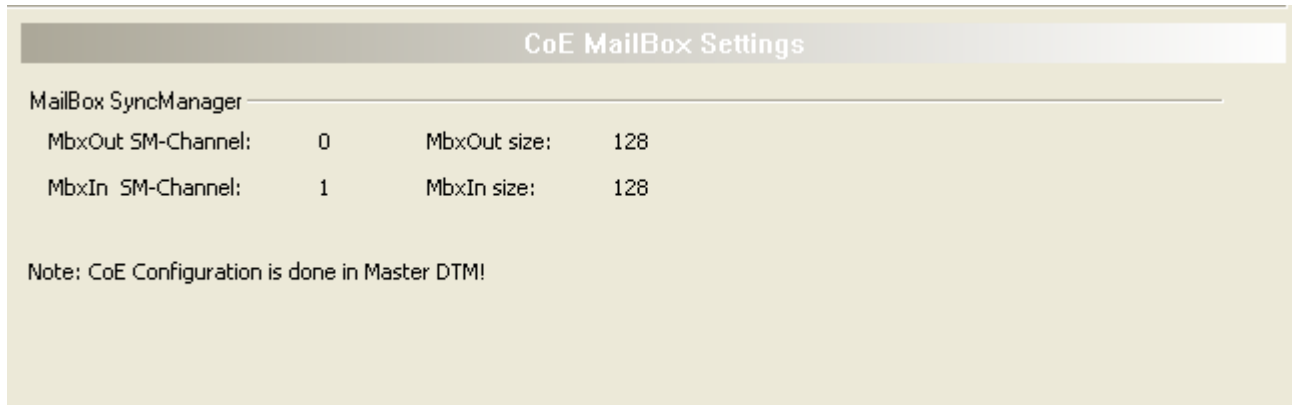


Figure 22: Configuration > Mailbox > CoE Mailbox Settings

The dialog page provides the following information:

- The channel number of the sync manager (for mailbox input and output)
- The configured mailbox size (this applies both for the input mailbox and for the output) mailbox

The complete MailBox configuration for each slave with MailBox support is done in the EtherCAT Master-DTM.

4 Description

4.1 Overview Description

The **Description** pages contain the following information:

- XML Viewer page: the devices XML file content in HTML style.

Description Dialog Pages

The table below informs about the contents of the **Description** dialog page:

Subsection	Manual Page
<i>XML DDF Viewer</i>	37

Table 18: Descriptions of the Description Pages

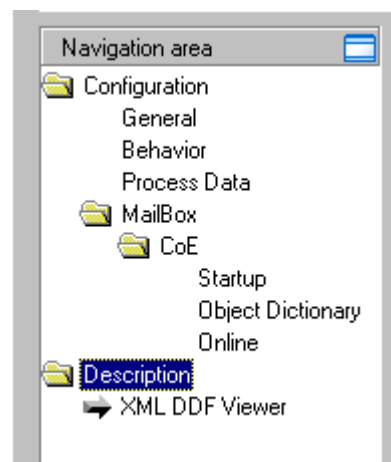


Figure 23: Navigation Area – Description

4.2 XML DDF Viewer

The **XML DDF Viewer** displays the content of the DDF file of the device which is stored in an XML format..

Under **Filename** the absolute file directory path and the file name of the displayed DDF file is displayed. **Find what** offers a search feature to search for text contents within the text of the DDF file.

In the DDF Viewer window on the left side, the line number is displayed for simple overview, the further entries show the DDF file in text format.

Parameter	Meaning
Filename	File directory path and the file name of the displayed DDF file.
Find what	Search feature to search for text contents within the text of the DDF file.
Match case	Search option
Match whole word	Search option

Table 19: Device Description – XML DDF Viewerr

The **XML DDF Viewer** page consists of the following elements:

- **File name** shows the absolute path of the DDF file.
- **Find what** offers searching for specific text within the DDF file.
- Using the **Find Next** button allows you to jump to the next occurrence of the text to be searched for within the XML DDF file.
- Check **Match case** if you want to perform a case-sensitive search.
- Check **Match whole word** if only entire words should match and fragments of words should be excluded from matching.



Note: You can also access the search functionality of the **XML DDF Viewer** by typing **Ctrl-F** on the keyboard.

5 Appendix

5.1 User Rights

User-rights are set within the FDT-container. Depending on the level the configuration is accessible by the user or read-only.

To access the **Configuration** panes of the generic EtherCAT Slave DTM you do not need special user rights. Also all users can select the decimal or hexadecimal Display mode or sort table entries.



Note: To edit, set or configure the parameters of the **Configuration** panes, you need user rights for *Maintenance*, for *Planning Engineer* or for *Administrator*.

The following tables give an overview of the user right groups and which user rights you need to configure the single parameters.

5.1.1 Configuration

	Observer	Operator	Maintenance	Planning Engineer	Administrator
<i>General</i>	D	D	X	X	X
<i>Behavior</i>	D	D	X	X	X
<i>Distributed Clock</i>	D	D	X	X	X
<i>Process Data</i>	D	D	X	X	X
<i>Mailbox</i>	D	D	X	X	X

Table 20: Configuration (D = Displaying, X = Editing, Configuring)

5.2 References

- [1] Device Type Manager (DTM) Style Guide, Version 1.0 ; FDT-JIG - Order No. <0001-0008-000>
- [2] EtherCAT Communication Specification, August 2007
- [3] EtherCAT Slave Protocol API Manual, Revision 3 (V4), Hilscher GmbH 2013
EtherCAT Slave Protocol API Manual, Revision 21 (V2), Hilscher GmbH 2013

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5.5 Glossary

CoE

CANopen over EtherCAT

CoE denominates a method for accessing an object dictionary which has been adopted for use in EtherCAT from CANopen.

DDF

Device Description File.

DTM

Device Type Manager.

The Device Type Manager (DTM) is a software module with graphical user interface for the configuration or for diagnosis of devices.

E²PROM

Electronically erasable Programmable Read-Only Memory

E-Bus

Bus system based on LVDS standard

EDS

Electronic Data Sheet

EtherCAT-Master

A device which is responsible for the configuration, parameterization of the EtherCAT segment, all connected devices' controllers, and cyclic process data exchange, mailbox and diagnostics services.

EtherCAT-Port

Physical type of data transmission used by EtherCAT. An EtherCAT Slave Master can have up to 4 EtherCAT ports. Can be one of the following three alternatives:

- E-Bus
- 100Base-TX
- 100Base-FX

EtherCAT-Slave

A device which is configured by the Master, receives telegrams with output data, commands from it and provides input and status data.

FDT

Field Device Tool

FDT specifies an interface, in order to be able to use DTM (Device Type Manager) in different applications of different manufacturers

FMMU

Fieldbus Memory Management Unit

A field bus memory management unit organizes a mapping of EtherCAT logical addresses to physical addresses.

LVDS

Low Voltage Differential Signals

A data transmission standard specified in ANSI/TIA/EIA-644-1995 and used in Beckhoff's E-Bus.

Object Dictionary

An object dictionary is a storage area for device parameter data structures. It is accessed in standardized manner very similarly as this is done in CANopen..

PDO

Process Data Objekt

Specific data object for cyclic data communication.

SDO

Service Data Objekt

Specific data object for acyclic data communication, i.e. mailbox-based communication. It is typically used for accessing the object dictionary.

Sync Manager

Synchronization Manager

A sync manager synchronizes the data communication on a specific communication channel. It is configured for managing either input or output and for working either cyclically or acyclically based on mailboxes. Configuration is done within the DDF file. Up to 4 sync managers numbered 0 to 3 can be configured.

XML

Extensible Markup Language

A versatile data storage format defined by the World Wide Web Consortium (W3C). It is based on elements and attributes. In EtherCAT, it is used in device descriptions stored in DDF files

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